Asymptotic dispersion in 2D heterogeneous porous media
determined by parallel numerical simulations

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[1] We determine the asymptotic dispersion coefficients in 2D exponentially correlated lognormally distributed permeability fields by using parallel computing. Fluid flow is computed by solving the flow equation discretized on a regular grid and transport triggered by advection and diffusion is simulated by a particle tracker. To obtain a well-defined asymptotic regime under ergodic conditions (initial plume size much larger than the correlation length of the permeability field), the characteristic dimension of the simulated computational domain was of the order of $10^5$ correlation lengths with a resolution of ten cells by correlation length. We determine numerically the asymptotic effective longitudinal and transverse dispersion coefficients over 100 simulations for a broad range of heterogeneities $\sigma^2 \in [0, 9]$, where $\sigma^2$ is the lognormal permeability variance. For purely advective transport, the asymptotic longitudinal dispersion coefficient depends linearly on $\sigma^2$ for $\sigma^2 < 1$ and quadratically on $\sigma^2$ for $\sigma^2 > 1$ and the asymptotic transverse dispersion coefficient is zero. Addition of homogeneous isotropic diffusion induces an increase of transverse dispersion and a decrease of longitudinal dispersion.


1. Introduction

[2] The determination of the large-scale dispersion coefficients has been widely debated in the last twenty years [Dagan, 1989; Gelhar, 1993]. The classical case is the lognormal permeability field with an exponential correlation function such as:

$$C(r) = \sigma^2 \exp\left(-\frac{|r|}{\lambda}\right)$$

(1)

where $\sigma^2$ is the lognormal permeability variance, $|r|$ is the distance between two points and $\lambda$ is the correlation length. Solute transport processes are advection and homogeneous isotropic diffusion. We look at the asymptotic dispersion coefficient for large heterogeneity corresponding to $\alpha^2 \in [1, 9]$. Numerical simulations did not previously lead to definitive solutions because of the large times and equivalent domain dimensions required for the convergence to the asymptotic regime.

[3] Two types of numerical simulations have been performed according to the derivation method of the velocity field. The velocity field is classically computed either directly from discretizing and solving the flow equation or from the first-order approximation of the flow equation. The computational domain is of dimensions $L_x$ and $L_y$ in the two spatial dimensions $x$ and $y$. $L_x$ and $L_y$ are counted in terms of correlation length. The correlation length $\lambda$ is counted in terms of grid cells. If we note $l_m$ the dimension of the grid cell, the ratios $L_x/\lambda$, $L_y/\lambda$ and $\lambda/l_m$ should be as large as possible. Discretizing the flow equation yields a linear system of order proportional to the number of grid cells whatever the finite difference or finite element scheme [Bellin et al., 1992; Cvetkovic et al., 1996; Hassan et al., 2002; Salandin and Fiorotto, 1998; Trefry et al., 2003] (Details of numerical simulations are given in Table 1). It explains why the direct solving of the flow equation has been limited to some $10^5$ cells number. It corresponds to some tens of exploitable correlation lengths that turn out to be not enough for determining directly the asymptotic dispersion coefficient. Convergence to the asymptotic regime is slow requiring very large simulations [Bellin et al., 1992]. This study also shows a pronounced realization effect also obtained in [Trefry et al., 2003]. The realization effect consists first in large dispersion coefficient variations and secondly in deviations from the mean behavior. It has two implications. First, the second-order moment of the solute plume requires a large number of Monte-Carlo realizations and particles to achieve convergence. Secondly, it emphasizes the problem of the relevance of the mean behavior to natural cases which are inherently single realizations requiring conditioning on measurements and the use of an inverse problem methodology.

[4] The other simulation method consists in deriving the velocity field from the first order approximation of the flow equation and performing subsequently a particle tracking [Bellin et al., 1992; Dentz et al., 2002; Rubin, 1990; Schwarze et al., 2001] (Table 1). This methodology does not require a grid and shortcuts the linear system solving...
The asymptotic regime, we use very large computational domains (100 times larger than the largest previously studied) under ergodic conditions (large plume sizes compared to the correlation length of the permeability field). We compare our results to the previous numerical results and analytical predictions.

2. Numerical Methods

2.1. Assumptions and Notations

We study 2D heterogeneous permeability field following a lognormal exponentially correlated distribution as stated in the introduction (Equation (1)). We perform the study on a large range of $\sigma^2$ values ($\alpha^2 \in [0.25, 9]$) first step. Very long particle paths can be simulated and the asymptotic coefficients can be determined. In practice the average particle path length reached by this method is around hundred times larger than that obtained by the previous direct simulation method with a resolution five times finer (Table 1). However, this methodology is limited to the validity domain of the first-order approximation ($\sigma^2 < 1$). For larger heterogeneities, deviations of the velocity field from the normal behavior are non negligible and increase with $\sigma^2$ [Salandin and Fiorotto, 1998]. The longitudinal velocity distribution becomes asymmetrical and is between the normal and lognormal distributions. The transverse velocity distribution becomes flatter with larger tails than that of the normal distribution. The first-order approximation of the velocity field does not capture these effects. Moreover, the use of first-order approximated velocity field may lead to erroneous numerical results. In fact, for even not too large heterogeneity ($\sigma^2 = 1$), the first-order approximation produces closed streamlines in which particles can enter either by advection or by diffusion increasing artificially dispersion [Dentz et al., 2003].

Neither the direct solution nor the first-order approximation of the flow simulation have led to direct numerical estimates of the asymptotic transverse and longitudinal dispersion coefficients for broad heterogeneous permeability fields ($\sigma^2 > 1$). The only numerical estimate is provided by Dagan et al. [1988] and concerns the dependence of the asymptotic longitudinal dispersion coefficient $D_{LA}$ on $\sigma^2$. They assume that the Lagrangian integral scale $\lambda_{xx}$ is independent of $\sigma^2$ and estimate numerically the Lagrangian velocity variance $\sigma_{xx}^2(0)$. As $D_{LA} \approx \lambda_{xx} \cdot u_{xx}(0)$ in the asymptotic regime, they found $D_{LA} \propto \sigma^2$ with $\beta = 2.06, 2.19, 2.29$, and $2.35$ respectively for $\sigma^2$ in the intervals $[0.05, 1], [1, 2], [2, 3]$ and $[3, 4]$.

Analytical estimates of the dispersion coefficient come from first-order and second-order approximations of the flow and transport equations. First-order approximations yield a linear dependence of the asymptotic longitudinal dispersion coefficient $D_{LA}$ on $\sigma^2$ and a zero asymptotic transverse dispersion coefficient $D_{TA}$ for purely advected solutes [Gelhar, 1993]:

$$D_{LA} = u \cdot \lambda_{xx} \cdot \sigma^2$$

$$D_{TA} = 0$$

where $u$ is the mean velocity. Adding diffusion slightly reduces the asymptotic dispersion coefficient $D_{LA}$ for isotropic diffusion and $Pe$ larger than 10 [Fiori, 1996]. Second-order approximation of the transport equation has been taken into account and confirms the zero asymptotic transverse dispersion coefficient [Hsu et al., 1996]. For the longitudinal dispersion coefficient and values of $\sigma^2$ larger than 1 ($\sigma^2 = 1.6$ in [Bellin et al., 1992]), first-order approximations of the flow and transport equations remain very close to numerical results [Dagan et al., 2003]. Adding a second-order term does not improve the approximation of the longitudinal dispersion coefficient but on the contrary deteriorates it. It has thus been deduced that the independent linearizations of flow and transport induce opposite deviations from linear theoretical results that partly cancel out each other. These conclusions concerning both the zero asymptotic transverse dispersion coefficient and the performance of the first-order approximation were confirmed on slightly different heterogeneous media consisting in spherical inclusions in a homogeneous medium [Dagan et al., 2003; Jankovic et al., 2003]. Other theoretical frameworks have been used to estimate the 2D asymptotic transverse dispersion coefficient $D_{TA}$. Using volume averaging, $D_{TA}$ is null like with the first-order approximation [Attinger et al., 2004], whereas $D_{TA}$ is not null by using the conjecture of Corssin [Dentz et al., 2002].

In this article, we compute the effective asymptotic longitudinal and transverse dispersion coefficients for large heterogeneities ($\alpha^2 \in [0.25, 9]$) both for pure advection and homogeneous isotropic diffusion cases. To reach the asymptotic regime, we use very large computational domains (100 times larger than the largest previously studied) under ergodic conditions (large plume sizes compared to the correlation length of the permeability field). We compare our results to the previous numerical results and analytical predictions.

| Table 1. Characteristics of 2D Flow and Transport Simulations* |
|------------------|---|---|---|---|---|---|---|
| FCM | TP | TCM | $\sigma^2$ | $\lambda_{m}$ | $L_x/L_{m}$ | $L_y/L_{m}$ | $N_{m}$ | MC | PT |
| [Rubin, 1990] | 1st | A | PT | 0.79 | 8 | 36 | 18 | 4 | 10$^8$ | MC-PT = 1500 |
| [Bellin et al., 1992] | full | A | PT | [0.1, 1.6] | 4 | 24 | 18 | 7 | 10$^6$ | 500-1000 | 1 |
| [Cvetkovic et al., 1996] | full | A | PT | [0.4] | 50 | 5000 | | | |
| [Salandin and Fiorotto, 1998] | full | A | PT | [0.05, 4] | 50 | 25 | 5 | 10$^4$ | 2000-3000 | |
| [Schwarze et al., 2001] | 1st | AD | PT | [0.1, 1] | 50 | 5000 | | | |
| [Hassan et al., 2002] | full | A | PT | [0.25, 2.25] | 5 | 25 | 3 | 10$^2$ | 2000-3000 | |
| [Dentz et al., 2002] | 1st | AD | PT | [0.1, 2] | 50 | 1500 | | | 2000 |
| [Trefry et al., 2003] | full | A | NS | [0.25, 4] | 82 | 100 | 1 | 10$^4$ | 100 |
| this study | full | AD | PT | [0.25, 8] | 10 | 819-1638 | 819 | 7 | 10$^4$-1.4 10$^4$ |

*FCM stands for flow computation method. It can be 1st order when flow is obtained by first order approximation of the flow equation or full when flow is obtained by solving directly the full discretized flow equation. TP is the transport processes accounted for (A for advection, D for diffusion, $\alpha$ for dispersion). TCM stands for transport computation method (PT for particle tracking, NS for numerical scheme). $N_x$ and $N_y$ are the number of correlation lengths within the domain respectively in the main direction of flow and perpendicularly to it. $V_{n_{x,y}}$ is the total number of cells ($N_{x,y} = L_x/L_{y}/2$). MC realizations is the number of Monte-Carlo realizations per parameter set. PT trajectories is the total number of analyzed trajectories per realization when particle tracking is used.
because broad-range heterogeneities have been observed in the field (for example $\sigma^2 \sim 5$ for the Columbus site [Rehfeldt et al., 1992]) and secondly to test theoretical predictions. Solute are transported by advection and diffusion. Diffusion is homogeneous with a diffusion coefficient noted $d$, the Peclet number $Pe$ expressing the ratio between advection and diffusion is equal to $Pe = (\lambda \cdot u)/d$, where $u$ is the mean velocity.

[9] As seen in introduction, discretizing and solving the flow equation for obtaining the velocity field computation is necessary for large heterogeneities ($\sigma^2 > 1$). From previous simulation results obtained by using the first-order approximated velocity field (Table 1), the necessary domain dimensions to asymptotic regime is around a thousand of correlation lengths with a resolution of around 10 cells by correlation length [Ababou et al., 1989] leading to a number of cells of the order of $10^8$. Such large domains require parallel computing.

2.2. Permeability Field Generation

[10] The software must be fully parallelized as the computational domain itself cannot be stored on a unique processor. The computational domain is distributed from the beginning to the end of the simulation, according to a domain decomposition in vertical slices (Figure 1). Each processor owns a well-defined part of the array corresponding to a sub-domain and keeps in local memory one layer of cells surrounding its sub-domain. These cells called “ghost cells” are necessary for the determination of the inter-cell permeability on sub-domain boundary cells. The additional cost of memory use is negligible and the communication cost between neighboring processors is reduced.

[11] The generation of the correlated lognormal field is performed via a Fourier transform [Gutjahr, 1989]. We use the software FFTW [Frigo and Johnson, 2005]. This library has a variety of composable solvers representing different FFT algorithms and implementation strategies, whose combination into a particular plan for a given size can be determined at runtime according to the characteristics of the machine/compiler in use. The construction of the permeability field ends up with filling up the ghost cells, requiring the management of some communication between the processors. Permeability, velocity components and head values are all stored on the same types of array. The permeability field obtained from the Fourier transform methodology gives the right correlation length. The obtained variance is generally slightly smaller than the targeted variance [Yao, 2004]. More precisely, the variance is lowered by half the value of the mean. To avoid this bias we first generate a Gaussian correlated random field with zero mean and unitary variance. As we use a zero mean, the output variance is equal to the input targeted one. To obtain the right field, we first multiply the generated field by the standard deviation and add the logarithm of the geometric mean. We secondly take the exponential of the result. We calculated the obtained variance and found a value close at 0, 02% to the input one for $8192^2$ grids.

2.3. Flow Computation

[12] We discretize the classical flow equation $\nabla(K \nabla h) = 0$ with $K$ and $h$ the permeability and hydraulic head and apply permeameter-like boundary conditions consisting in fixed head-on two opposite borders and no flow on the perpendicular borders (Figure 1). The flow equation is discretized according to a finite difference scheme with harmonic inter-cell permeabilities. For regular square grids, this scheme is equivalent to mixed hybrid finite elements [Chavent and Roberts, 1991]. This equivalence ensures to these finite differences the high precision of the mixed hybrid finite elements useful for large permeability contrasts [Mose et al., 1994]. The discrete flow equations end up to a linear system $Ax = b$, where $A$ is a symmetric positive definite sparse structured matrix. The order of $A$ is equal to the number of cells. The choice of the linear solver is essential to achieve the CPU and memory requirements for such large computational domains.
free, heavily used, portable and parallel [AMG (Algebraic MultiGrid) whose advantages are to be
A numerical library HYPRE and more precisely Boomer-
CPU time, we chose an iterative multigrid method. We used
numbers with Figure 2.
iterative and semi-iterative [systems. They can be divided into three classes: direct,
condition numbers [themselves or as pre-conditioners, but are sensitive to
efficient and scalable, well-suited to regular grids, used by
competitive. Iterative methods of multigrid type are often
memory but need a scalable preconditioner to remain
Direct methods are highly efficient but require a large
memory space. Iterative methods of Krylov type require
Diffusion is simulated by adding a random
interpolations. Diffusion is simulated by adding a random
the time step is either proportional to the local advection
velocity magnitude of the crossed cells. More precisely,
time and of the diffusion coefficient [displacement of length proportional to the square root of
intersections. Under this assumption of homogeneous isotropic
diffusion, this method correctly models diffusion and does not require any correction of the velocity term necessary for
taking into account diffusion discontinuities [Delay et al., 2005]. Between \( t \) and \( t + dt \), a particle moves from positions M(\( t \)) to M(\( t + dt \)) by advection and diffusion:
\[
M(t + dt) = M(t) + v[M(t)] \cdot dt + \sqrt{2 \cdot d \cdot dt \cdot Z \cdot r}
\]
where \( v[M(t)] \) is the velocity at the position \( M \), \( d \) is the
diffusion coefficient, \( Z \) is a random number drawn from a
Gaussian distribution of mean 0 and variance 1 and \( r \) is a
unitary vector with uniformly distributed orientation. The
time step evolves along the particle path according to the
velocity magnitude of the crossed cells. More precisely,
time step is either proportional to the local advection
time equal to the cell size \( l_m \) divided by the maximum of the
velocities computed on the cell borders noted \( v_x, v_y \), \( v_{x+}, v_{y-} \),
in the \( x \) and \( y \) directions or to the diffusion time
necessary to cross the cell:
\[
dt = \frac{1}{N_a} \cdot \min \left[ \frac{l_m}{\max(v_x, v_y, v_{x+}, v_{y-})}, \frac{\ell_m}{2d} \right]
\]
\( N_a \) is a positive integer representing the order of the time
step number performed by the particle in the cell. In the
simulations \( N_a \) is set to 10, meaning that the particle makes
of the order of 10 steps to cross the cell. The velocity
\( v[M(t)] \) is obtained from a bilinear interpolation as it is the
sole interpolation method that ensures mass conservation
[Pollock, 1988]. It is important to find the exit position of
the particle from the cell in order that particles always move
in the cell with the velocity characteristics of the current cell
and not of the previous one [Pokrajac and Lazic, 2002].
The exit point and time from the cell are found by linear
interpolations. Diffusion is simulated by adding a random
displacement of length proportional to the square root of
time and of the diffusion coefficient [Tompson and Gelhar,
1990].

[14] Transport is simulated by a particle tracker algorithm
[Delay et al., 2005]. Particle tracking is well suited for pure
advection and advection-dominated transport processes
because it does not introduce spurious numerical diffusion.
Advection is simulated by a first order explicit scheme. We
tried higher-order schemes which led to very small differences.
Under this assumption of homogeneous isotropic
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M(t + dt) = M(t) + v[M(t)] \cdot dt + \sqrt{2 \cdot d \cdot dt \cdot Z \cdot r}
\]

\[\ell_m = 6.25\]
\[L_y = 819,2\]
\[N = 819,2, \lambda = 10 \, l_m\text{ and } L_x = 819,2, \lambda = 819,2. \lambda\text{ (pure advection case).}

With this method, the CPU time is indeed not sensitive
to the permeability variance. For a grid of 1.3 10^{7} nodes
with \( \sigma^2 = 6.25 \), the flow computation requires around half
an hour on a cluster of a 32 bi-processor AMD Opteron 2.2
GHz with 2 Go RAM each interfaced by Gigabit Ethernet.

2.4. Transport Simulation

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time step evolves along the particle path according to the
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The exit point and time from the cell are found by linear
interpolations. Diffusion is simulated by adding a random
displacement of length proportional to the square root of
time and of the diffusion coefficient [Tompson and Gelhar,
1990].

[15] To avoid border effects, particles are introduced at a
distance 0.05 \( L_x \) from the left border (input border) of the
computational domain (Figure 1) corresponding for \( L_x = 8192 \, l_m \text{ and } L_y = 16384 \, l_m \text{ and } \lambda = 10 \, l_m \) (10 cells by
correlation length) to respectively 40 and 80 correlation
lengths downstream from the fixed head boundary. Particles
are stopped when arriving at the same distance upstream

![Figure 2.](image-url)
was at most equal to the time required for the computation of flow.

3. Dispersion Computation, Convergence and Validation

Simulations give the first two moments of the particle plume distribution $\langle x(t) \rangle_i$ and $\langle x^2(t) \rangle_i$, here expressed in the longitudinal direction $x$:

$$\langle x^k(t) \rangle_i = \frac{1}{N_p} \sum_{j=1}^{N_p} x_j(t)^k$$  \hspace{1cm} (3)

with $i$ the simulation number, $x_j(t)$ the abscissa of the particle $j$, $k$ the moment order (1 or 2), and $N_p$ the number of particles. We compute a normalized dispersion coefficient by using the classical formula

$$D_L(t) = \frac{1}{u \lambda} 2 \frac{d \langle x^2(t) \rangle_i - \langle x(t) \rangle_i^2}{dt}$$  \hspace{1cm} (4)

and discretize it on the successive time steps. The normalization factor $u \lambda$ is logical in terms of dimension to obtain a non-dimensional result. It is further justified for $\sigma^2 < 1$ by the first-order longitudinal dispersion coefficient linear in $x$. From the right border (output border). For all simulations, the injection window is a thin line perpendicular to the mean flow direction of length equal to $3277 \lambda_m$ (i.e., 0.4 $L_x$ or around 328 correlation lengths for $\lambda = 10 \lambda_m$). Particles are injected with a uniform distribution within the injection window. The extension of the injection window is large enough to ensure a broad sampling of the velocity field but narrow enough to prevent particles from sampling the zones close to the no-flow boundary conditions [Salandin and Fiorotto, 1998]. The number of particles approaching the no-flow border of the domain by less than 15% of the domain dimension (120 correlation lengths) is recorded and found to be null. This “exclusion zone” close to the no-flow boundaries is shown on Figure 1. The particle-tracking algorithm has been adapted for parallel simulations with the domain stored on the different processors [Beaudoin et al., 2007]. The time necessary for the simulation transport

Figure 3. Asymptotic longitudinal (a) and transverse (b) dispersion coefficients as functions of the particle number $N_p$ for $L_x = 1638, 4 \lambda$ and $L_y = 819, 2 \lambda$. In this figure as well as in the following figures, the term advection in the legend refers to the pure advection case without diffusion and the legend is the same for both graphs.

Figure 4. (a) Asymptotic longitudinal dispersion coefficient and (b) standard deviation of the dispersion coefficient at a given time $t_N = 600$ as functions of the number of simulations for $L_x = 1638, 4 \lambda$ and $L_y = 819, 2 \lambda$. In (a), the dispersion coefficient $D_L$ for $t_N = 600$ has been added for the pure advection cases. $t_N = 600$ is taken in the second half of the signal as the full signal length is around $t_N = 1000$. 
3.1. Asymptotic Dispersion Coefficient

For the transverse dispersion coefficient, we derived the asymptotic limit, where its asymptotic behavior of the dispersion coefficient can be well approached with exponential function 

\[ D_L(t) = \frac{L^2}{\lambda t} \exp\left(-\frac{t}{t_N}\right) \]

where \( D_L(t) \) is the asymptotic dispersion coefficient, \( t_N \) is a characteristic convergence time to the asymptotic regime.

For the transverse dispersion coefficient, we derived the realization-based coefficient \( D_L(t_N) \) by using the same methodology applying Equation (3) where we replace \( x \) by \( y \). Because of the absence of any systematic time evolution, we determine the asymptotic dispersion coefficient by averaging over the second part of the time range \([0.5t_{fb}, t_{fb}]\) like for the longitudinal dispersion coefficient. Whatever the method, the key point is to simulate transport in a sufficiently large domain to observe the stabilization of dispersion on a time range long enough. The relevance of the asymptotic dispersion coefficient depends on the domain dimensions counted in terms of correlation length \( L_x/\lambda \) and \( L_y/\lambda \).

\[ \sigma_{DL}(t) = \frac{\sigma_{DL}(t_{fb})}{\sqrt{NS}} \]

where \( \sigma_{DL}(t) \) is the asymptotic dispersion coefficient, \( NS \) is the number of simulations, \( \sigma_{DL}(t_{fb}) \) is the standard deviation from the previous moments. The ensemble dispersion is obtained by first computing the derivative of the standard deviation of the plume concentration within a simulation and secondly by averaging the computed standard deviations over the \( NS \) simulations. The ensemble dispersion is obtained by first computing the two first moments of the plume concentrations over the \( NS \) simulations and by secondly computing the derivative of the standard deviation from the previous moments. The ensemble dispersion is larger than the effective dispersion as it measures the plume dispersion with respect to the plume position averaged over all simulations whereas the effective dispersion measures the plume dispersion in each simulation with respect to the simulation mean plume position [Dentz et al., 2000].

3.2. Convergence With the Number of Particles \( N_p \)

\[ \frac{\sigma_{DL}(t_{fb})}{\sqrt{NS}} = \frac{\sigma_{DL}(t_{fb})}{\sqrt{N_p}} \]

where \( \sigma_{DL}(t_{fb}) \) is the asymptotic dispersion coefficient, \( N_p \) is the number of particles. Increasing the number of particles \( N_p \) does not change the global tendencies of the dispersion coefficients. Finally between 5000 and 10,000 particles over 1000 does not change the global tendencies of the dispersion coefficients.

\[ \frac{\sigma_{DL}(t_{fb})}{\sqrt{NS}} \approx \frac{\sigma_{DL}(t_{fb})}{\sqrt{N_p}} \]

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where \( \sigma_{DL}(t_{fb}) \) is the asymptotic dispersion coefficient, \( N_p \) is the number of particles. Increasing the number of particles \( N_p \) does not change the global tendencies of the dispersion coefficients.
precisely, they vary respectively by less than 5% and 10% whatever the case. There is no systematic tendency either with the number of particles or with the Péclet number. We kept for the pure-advection case 10,000 particles and for the advection-diffusion case 2000 particles. As convergence is not faster without diffusion as shown by Figure 3, this choice does not advantage the pure advection case more than the 5% and 10% precisions previously found. The global number of particles can be converted into number of particles by correlation length at injection time. For all cases the injection window was set to 3277 $\lambda$. For the pure-advection case $N_p = 10,000$, the number of particles by cell is 3 on average and the number of particles by correlation length is 30 on average because there are 10 cells by correlation length ($\lambda = 10 \; \lambda_m$). For the advection-diffusion case $N_p = 2000$, the number of particles by cell is 0.6 on average and with $\lambda = 10 \; \lambda_m$, the number of particles by correlation length is 6 on average.

3.3. Convergence With the Number of Simulations $N_S$

We study the convergence of the average and standard deviation of the dispersion coefficients with the number of simulations $N_S$ for the most heterogeneous cases $\sigma^2 = 6.25$ and 9. The mean longitudinal asymptotic dispersion coefficient is very close to the mean of the dispersion coefficient taken at a given time $t_N = 600$ (Figure 4a, solid and open squares compared to thick solid and dashed grey lines). The asymptotic dispersion coefficient converges very rapidly for $N_S \geq 20$. The largest difference between values for 20 and 100 simulations is of the order of 2.5%. The standard deviation of the longitudinal dispersion coefficient

**Figure 6.** Normalized longitudinal dispersion coefficient for single realizations $D_L^j(t_N)$ (points), their averages $D_L(t_N)$ over 100 realizations (lines) and the confidence interval at 95% on the dispersion coefficient (dashed line) ($\sigma^2 = 1$ and 9, pure advection case). The dashed-dotted line represents the normalized apparent dispersion coefficient $D_{app}(t) = 0.5 \langle \chi^2(t) \rangle / t$. Computational domain size are for $\sigma^2 = 1$ (a) $L_x = L_y = 819$, 2 $\lambda$ and for $\sigma^2 = 9$ (b) $L_x = 1638$, 4 $\lambda$ and $L_y = 819$, 2 $\lambda$.
at the same given time $t_N = 600$ s ($DL(t_N = 600)$) displays relative larger variations with the number of simulations $N_S$ (Figure 4b, lines and symbols). The maximal variation between $N_S = 20$ and $N_S = 100$ is 20%. As variations are not monotonous, the value for the largest number of simulations cannot be more precise than 20%. We note that both the variability of the average asymptotic dispersion coefficients and the standard deviation of the dispersion coefficient decrease with more diffusion (smaller Peclet numbers). Convergence of the longitudinal dispersion coefficient with the number of simulations is thus faster with more diffusion.

Tendencies for the transverse dispersion coefficient are quite different. For $N_S \geq 20$, the asymptotic dispersion coefficient is very close to zero for the pure-advection case (Figure 5a) whereas the standard deviation of the transverse dispersion coefficient at a given time is much larger around 0.6 (Figure 5b). More diffusion corresponding to smaller Peclet numbers induces larger transverse asymptotic dispersion and standard deviation. The asymptotic transverse dispersion coefficient (Figure 5a) converges quickly and its

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**Figure 7.** Normalized transverse dispersion coefficient. Same parameters as in Figure 6.

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**Figure 8.** Velocity variance $u_{xx}$ and $u_{yy}$ as functions of $\sigma^2$ obtained analytically by Rubin [1990] and numerically in the present study and by Salandin and Fiorotto [1998].

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**Figure 9.** Asymptotic longitudinal dispersion coefficient as a function of the correlation length for the pure advection case. Lines are linear fit through 0. Same parameters as in Figure 6.

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**Figure 10.** Longitudinal mean dispersion coefficient as a function of $t_N$ for the pure advection case (time in terms of correlation scales crossed by the plume). Dashed lines mark the asymptotic coefficients. Same parameters as in Figure 6.
variations for $N_S \geq 20$ are less than 10% of its mean value. The standard deviation (Figure 5b) still varies non monotonously and the amplitude of its variations can reach 25% of its mean value.

In the two previous sections, we have fixed the mesh size $l_m$ and analyzed the convergence of the random walker and the Monte-Carlo simulations. For a given simulation, we verified numerically that the random walker converges when we increase the number of particles. More precisely, the dispersion coefficients $D_L(t)$ and $D_T(t)$ converge. We can assume a convergence in an appropriate norm; in view of the numerical results, we can also assume a uniform convergence, independent of the simulations. For a given number of particles, we verified numerically that the Monte-Carlo simulations converge when we increase the number of simulations. More precisely, we observe the convergence of the approximate first moments of the dispersion, computed with a given number of particles. Therefore we can assume that, for a given mesh size $l_m$, our numerical Monte-Carlo simulations give an accurate estimation of the first moments of the two dispersion functions. However, in our simulations, the second moments do not converge correctly. There may be different reasons for this lack convergence. First the number of Monte-Carlo simulations $N_S$ may not be large enough. Secondly dispersion coefficient may be affected by the finite volume method used for flow computation and the use of a bilinear interpolation for the velocity in the particle tracker. Thirdly, it may come from the generation of the permeability field from a truncated Fourier expansion and the assumption of a constant permeability in each grid cell. The same lack of convergence of the dispersion fluctuations has already been observed and related to the finite number of Fourier modes [Figure 5 of Eberhard, 2004].

In the following, we perform 100 simulations to ensure convergence of the first moments $D_L$ and $D_T$ for each parameter set. We keep the same parameters for all simulations. As the variations of both the longitudinal and transverse dispersion coefficients are stronger for $\sigma^2 = 9$ than for $\sigma^2 = 6.25$, we checked that convergence is at least as good for lower heterogeneities corresponding to $\sigma^2 \leq 6.25$.

3.4. Convergence of Dispersion Coefficients With Time

The domain dimensions were chosen in order to have a stabilization of the mean dispersion coefficient as a function time $D_L(t_{N})$ over at least half the time duration of the simulation, the maximal simulation time $t_{fb}$ being the first breakthrough time (time for which the first particle arrives at a distance of 0.05$L_x$ from the output border). The asymptotic regime is maintained over around 500 time units or equivalently on a spatial range of 500 correlation lengths. The simulations performed on domain of longitudinal dimension $L_x = 819, 2 \lambda$ with $\lambda = 10 l_m$ were large enough for $\sigma^2 \leq 4$. For $\sigma^2 = 1$, the asymptotic regime is reached.
after some tens of correlation lengths (Figure 6a). However, for \( \sigma^2 \geq 6.25 \), domains had to be twice longer \( (L_x = 1638, 4 \lambda) \) to obtain the same stabilization time range (Figure 6b). Such long stabilization times have also been observed in systems made of highly heterogeneous inclusions [Jankovic et al., 2006]. Large domain dimensions are required not only for large values of \( \sigma^2 \) but also for smaller values of \( \sigma^2 \) (values around 1), although it is not obvious on Figure 6a. In fact we performed the same simulations for domains of dimensions \( L_x = 102, 4 \lambda \) by \( L_y = 51, 2 \lambda \) and found that the asymptotic regime is far from being reached although the number of exploitable correlation lengths \((\sim 80)\) is large enough. There may be two reasons. First the asymptotic regime is difficult to identify over some tens of correlation lengths. Secondly, the injection window is smaller \((20 \text{ correlation lengths at } L_y = 512 \lambda \text{ compared to } 327 \text{ at } L_y = 8192 \lambda)\) inducing from the beginning a lower sampling of the velocity field and a larger convergence time to the asymptotic regime.

[25] The mean \( D_L(t_N) \) and the confidence interval at 95% derived from the mean and standard deviation are represented on Figure 6 (solid and dashed lines). \( D_L(t_N) \) displays a large variability but no definite trend whatever \( \sigma^2 \) as shown by Figure 6 (square and circle symbols). The average \( D_L(t_N) \) of the dispersion coefficient over 100 simulations represented by the black line smoothes the variations and indeed reaches a constant value at small times \( (t_N > 30) \) for \( \sigma^2 = 1 \) (Figure 6a) and at larger times \( (t_N > 400) \) for \( \sigma^2 = 9 \) (Figure 6b). The asymptotic regime is well approached at least during the second half of the simulation time, i.e., in the interval \([0.5 t_{fb}, t_{fb}]\). The realization-based \( D_L(t) \) displays a strong variability around 0 but no trend, not even at small times (square and circle points on Figure 7). The average over simulations (solid line of Figure 7) does neither show any trend whereas the standard deviation (dashed lines of Figure 7) is large compared to the average values.

[26] We note that several studies have used the apparent dispersion coefficient \( D_{app}(t) = 0.5 \langle \dot{x}^2(t) \rangle / t \) instead of the derivative (4) to remove the oscillations of the time derivative [Schwarze et al., 2001; Trefry et al., 2003]. Even though \( D_{app} \) tends to the effective dispersion coefficient (4) for large times, the differences between these two quantities are important and remain for very large times especially in the high variance case as shown by Figure 6 on the simulation averages (dashed-dotted lines compared to solid lines). We thus decide to determine the asymptotic dispersion coefficient \( D_L,A \) from the time derivative signal (4).
3.5. Validation

[27] We validate the numerical procedures by comparing them to theoretical and other numerical existing results. First, for \( \sigma^2 < 1 \), we compare numerical results to first-order theoretical results of the correlation functions of the longitudinal and transverse velocity fields [Rubin, 1990, Equations 9 and 10] and of the asymptotic dispersion coefficients. The velocity correlation function is highly close at least than 5% to the first-order prediction for \( \sigma^2 < 1 \) and is close at less than 1.5% to the results of Salandin and Fiorotto [1998] for \( 1 < \sigma^2 < 4 \) (Figure 8).

[28] For the asymptotic longitudinal dispersion coefficient, the normalization by \( \lambda \sigma \) enables a direct comparison of \( D_{LA} \) numerical results with \( \sigma^2 \) for \( \sigma^2 < 1 \) with equation (14). The agreement is very good as, for \( \sigma^2 = 0.25 \), Equation (15) and numerical simulations give respectively 0.25 and 0.26. We compare also our results of longitudinal asymptotic dispersion coefficient in the interval \( 1 < \sigma^2 < 4 \) to the variation of \( D_{LA} \) with \( \sigma \) obtained by Salandin and Fiorotto [1998]. Salandin and Fiorotto [1998] found \( D_L \propto \sigma^3 \) with \( \beta = 2.06, 2.19, 2.29 \) and 2.35 respectively for \( \sigma^2 \) in the intervals \([0.05, 1]\), \([1, 2]\), \([2, 3]\) and \([3, 4]\). We find \( \beta = 2.07, 2.37 \) and 2.62 for \( \sigma^2 \) in the intervals \([0.05, 1]\), \([1, 2.25]\), and \([2.25, 4]\). We find a closer agreement in the first interval but a faster increase of the asymptotic dispersion coefficient for \( \sigma^2 > 1 \). This could be linked to the number of correlation lengths limited to 20 in Salandin and Fiorotto [1998]. For advective-diffusive transport, we validate the algorithm against the classical analytical solution obtained in the homogeneous medium case.

4. Results of Asymptotic Dispersion Coefficients

4.1. Pure Advection (Pe = \( \infty \))

[29] We determine the effect of the resolution scale defined by the number of cells by correlation length \( \lambda / l_m \). We perform the simulations at \( \lambda / l_m = 5, 10 \) and 20 when previous simulations used a maximum of 8 cells per correlation length (Table 1). We verify that the asymptotic longitudinal dispersion coefficient depends linearly on \( \lambda \) for all values of \( \sigma^2 \) (Figure 9) justifying furthermore the normalization of the dispersion coefficients by \( \lambda \sigma \). It also shows the weak dependency of the asymptotic dispersion coefficient on the resolution of the discretization even for high heterogeneities. 10 cells by correlation length give very similar results as 5 or 20 cells by correlation length.

[30] The asymptotic regime has been reached and maintained over at least 500 correlation lengths whatever the value of \( \sigma^2 \) (Figure 10) and the asymptotic values of the dispersion coefficients have been computed according to the procedure described in the previous section (Figure 11). Both methodologies of exponential fitting and averaging lead to similar results within an interval of 0% to 3%. The first-order estimate of the dispersion coefficient (2) remains close to the numerical value even for \( \sigma^2 = 1 \) and 2.25 whereas it is lower by respectively 10% and 25%. This good performance of first-order results for values of \( \sigma^2 \) significantly larger than 1 has been previously observed and explained [Bellin et al., 1992; Dagan et al., 2003]. The independent linearizations of flow and transport induce opposite deviations from linear theoretical results and may partly cancel out each other. This conclusion was confirmed on slightly different heterogeneous media consisting of spherical inclusions in a homogeneous medium [Dagan et al., 2003]. For larger heterogeneity, the departure from the first-order results increases with \( \sigma^2 \). Numerical results are respectively 50%, 90% and 150% larger than the linear estimates for \( \sigma^2 = 4, 6.25 \) and 9. \( D_{LA}(av) \) is well represented by the approximate function \( 0.7 \sigma^2 + 0.2 \sigma^2 \) for large heterogeneities (\( \sigma^2 > 1 \)) (dashed curve on Figure 11).

[31] For transverse dispersivity, numerical results show some variability around 0 without any systematic trend neither for the realization-based result nor for the average (Figures 7 and 12). The similar transverse dispersion evolution with time for \( \sigma^2 = 6.25 \) and 9 comes from the fact that realizations are performed with the same set of seeds for the random generator. The correlation patterns are thus identical while the magnitude of the heterogeneity changes. The asymptotic dispersion coefficients computed by averaging over the second half of the time chronicle \( D_{LA}(av) \) are close to zero without being systematically positive or negative (Figure 13) and the magnitude of the standard deviation is much larger than the average. These results lead us to conclude that the asymptotic transverse dispersion coefficient is zero on average whatever \( \sigma^2 \). This confirms theoretical conclusions obtained by volume averaging [Attinger et al., 2004].

[32] Figures 6 and 7 show a large variability around the average both for the longitudinal and transverse dispersion coefficients whatever the heterogeneity represented by the value of \( \sigma^2 \). The standard deviation of the transverse dispersion coefficient converges (Figure 14b) within the computation time, whereas the convergence is not obvious for the standard deviation of the longitudinal dispersion coefficient (Figure 14a). The apparent increase of the longitudinal dispersion coefficient remains limited to at most 30% in the time interval \([t_0/2, t_0]\), which is close to the imprecision of 20% obtained in Section 3.3 because of the use of a limited number of simulations (\( N_0 \)). Convergence would require both more realizations and longer systems. As the increase remains limited and as \( \sigma(D_l(t_0)) \) is not the main objective of the study, we did not go further on its characterization.

[33] Finally, we derive from the exponential fit of the longitudinal dispersion coefficient the characteristic convergence time to the asymptotic regime \( t_{n0} \) (Figure 15). \( t_{n0} \) does not have an absolute meaning as it depends on the width of the injection window. We rather use \( t_{n0} \) to compare convergence time between different values of \( \sigma^2 \) in the same conditions. \( t_{n0} \) increases exponentially with the permeability variance contrarily to the first-order theory prediction according to which \( t_{n0} \) does not depend on the medium heterogeneity \( \sigma^2 \).

4.2. Advection and Diffusion (Pe < \( \infty \))

[34] We computed the dispersion coefficient \( D_l(t_{n0}) \) for the two Peclet number \( Pe = 100 \) and 1000. \( D_l(t) \) reaches its asymptotic regime whatever the value of \( \sigma^2 \) (Figure 16). The time to reach the asymptotic dispersion \( t_{n0} \) is smaller than in the pure-advection regime even if \( t_{n0} \) values are highly dispersed. Diffusion modifies only slightly the asymptotic longitudinal dispersion coefficient \( D_{LA} \) for \( \sigma^2 \geq 1 \) and let it decrease for \( \sigma^2 > 1 \) (Table 2). For small values of \( \sigma^2 (\sigma^2 \geq 1) \), the influence of diffusion is negligible as previously found [Fiori, 1996]. For \( \sigma^2 = 1 \), the
additional dispersion induced by diffusion is not significant because the asymptotic dispersion coefficient for \( Pe = \infty \) (larger than 1) is ten times larger than 1/\( Pe \). For \( \sigma^2 > 1 \), the asymptotic dispersion coefficient decreases surprisingly with more diffusion. More diffusion induces less dispersion. The decrease can be significant. For \( \sigma^2 = 6.25 \), \( D_{LA} \) is 25% lower at \( Pe = 100 \) than its value at \( Pe = \infty \) (pure advection). For large heterogeneities, diffusion reduces the global dispersion. This behavior was expected by Gelhar [1993] (pages 221–222) and de Arcangelis et al. [1986] and may be explained by the following argument also invoked for percolation systems [Koplik et al., 1988]. Large dispersion is induced by the widely scattered velocity distribution. Diffusion introduces a cut-off to this distribution thus narrowing it and letting in turn the dispersion coefficient decrease. In other words, diffusion extracts particles from the very slow velocity zones and restricts the dispersion of particle in the medium. The transverse asymptotic dispersion coefficient \( D_{TA} \) keeps a more classical behavior by increasing with more diffusion (Table 2). However, the increase of \( D_{TA} \) can be much larger than the sole diffusion contribution 1/\( Pe \). For large heterogeneities \( \sigma^2 = 6.25 \) and for \( Pe = 100 \), \( D_{TA} \) is 20 times larger than 1/\( Pe \). The effect of diffusion and advection cannot be simply superposed but interact to produce a larger transverse dispersion.

### 5. Conclusion

[35] We determine the asymptotic dispersion coefficients for 2D exponentially correlated lognormal permeability fields on a broad range of lognormal permeability variance \( \sigma^2 \) (\( \sigma^2 \in [0.25, 9] \)). We use parallel computing for simulating fluid flow and particle transport on large domains of typical dimension from 800 to 1600 correlation lengths with a resolution of 10 cells by correlation length, where \( l_m \) is the cell characteristic dimension. Such large domains turned out to be necessary to observe the asymptotic regime on a sufficiently long time range for determining unambiguously the asymptotic dispersion coefficients. The asymptotic longitudinal and transverse dispersion coefficient \( D_{LA} \) and \( D_{TA} \) have been estimated on a realization basis by averaging over a traveled distance of at least 400 correlation lengths. We have tested an alternative derivation methodology for the asymptotic longitudinal dispersion coefficient \( D_{LA} \) by fitting the dispersion coefficient by an exponential function. Estimates of \( D_{LA} \) by both methodologies lead to very similar values. The characteristic time given by the exponential fit gives an estimate of the convergence speed to the asymptotic regime. Simulations show that it increases exponentially with the heterogeneity \( \sigma^2 \) and decreases with diffusion.

[36] For pure advection (\( Pe = \infty \)), the asymptotic longitudinal dispersion \( D_{LA} \) is larger than the first-order estimate for high heterogeneity. More precisely, for \( \sigma^2 \) equal to 4, 6.25 and 9, \( D_{LA} \) is larger by respectively 50%, 90% and 150% than the linear estimates. For \( \sigma^2 > 1 \), \( D_{LA} \) is well fitted by the function \( 0.7\sigma^2 + 0.2\sigma^2 \) showing a quadratic evolution in \( \sigma^2 \) for large heterogeneities. This departure from the first-order theory is probably related to the extreme flow channeling observed for high heterogeneity [Le Borgne et al., 2007; Moreno and Tsang, 1994; Salandin and Fiorotto, 1998]. Whatever the heterogeneity level, the asymptotic transverse dispersion coefficient is always zero as predicted by first-order theory for low heterogeneity and by volume averaging [Attinger et al., 2004].

[37] The addition of diffusion to advection leads to two very different behaviors for longitudinal and transverse dispersions. For large heterogeneities (\( \sigma^2 > 1 \)), diffusion induces a significant longitudinal dispersion decrease and a transverse dispersion increase larger than expected. At most, for a Pe number of 100 (advection on average hundred times larger than diffusion) and a permeability variance \( \sigma^2 = 9 \), the longitudinal dispersion decreases by a factor of 2 and the transverse dispersion is 7.5 times larger than the local diffusion.

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