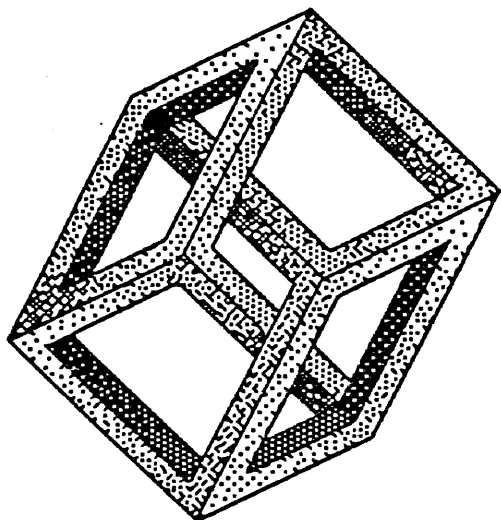


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**GENERATION OF ADA CODE  
FROM PETRI NETS MODELS**

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# Generation of ADA code from Petri Nets models

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## Résumé

Nous présentons une méthode automatique de **génération de code efficace**. Le code **ADA** est obtenu à partir d'un modèle formel décrit en réseaux de Petri exprimant le schéma de contrôle de l'application parallèle.

La méthodologie repose sur la décomposition de l'implémentation en 3 phases permettant l'intégration progressive des contraintes liées à l'application, à son environnement et au langage de programmation.

Nous introduisons une technique originale pour tendre vers une implantation **optimale**, minimisant le nombre de tâches supportant l'exécution de l'application tout en conservant le degré de parallélisme potentiel du modèle. L'idée majeure consiste à réutiliser les invariants produits par l'étape de validation du modèle pour déterminer le nombre minimal de tâches. Cette technique permet la caractérisation des types d'objets utilisés par l'implantation.

Nous appliquons la méthode proposée à un modèle conçu spécialement pour couvrir l'ensemble des problèmes soulevés, et nécessitant l'ensemble des différents types d'objets.

## Abstract

We propose a automatic method for the **generation of efficient code**. The **ADA code** is produced from a formal model using **Petri nets**. The formal model describes the control scheme of the parallel application.

Our methodology organizes the implementation into 3 steps that allow the progressive integration of the constraints of the application, of the environment, and of the programming language.

We introduce a new technique to tend towards an **optimal implementation** that minimizes the number of processes. This set of processes, that support the execution of the application, must keep the intrinsic parallelism of the model. The major idea is to reuse the linear invariants given by the validation of the model. These invariants allow us to define the optimal process number. This technique characterizes the objects used by the implementation steps.

We apply our method on a model which has been especially built to cover many technical problems and to include all the characterized object types.

## 1. INTRODUCTION

The parallel systems and their complexity have brought to the fore the advantages obtained during the conceiving stage by **formal models**. Supported by strict mathematical results, this kind of model enables the characteristics and the parameters of the system to be studied before its implementation.

**Petri Nets**, as a formal model, has already demonstrated its appropriateness to solve the problems raised by the study of distributed systems [Ayache 85]. But code generation is a very important point to allow Petri nets to be used in industrial environments. Activities in this area have a tradition in the context of Programmable Logic Controllers, for centralized logic automation applications.

Code generation in software applications has recently become most interesting because of the emergence of parallel architectures and new programming paradigms and objectives. Imperative programming is chosen most of the time, for example : ADA [Colom 86], CHILL, OCCAM [Steinmetz 86] and others [Nelson 83]. For specially tailored classes of nets, an object-oriented programming paradigm is being explored for Petri net model prototype implementation [Bruno 86]. Special characteristics and architecture of some distributed applications (for example telecommunications) allow the use of even more direct implementation.

The objectives of the project **PN\_TAGADA** (Petri Net \_ Translation, Analysis and Generation of ADA code) are to design and implement tools performing code generation in a context of distributed architecture. So we need to design and implement a tool for producing semi-automatically efficient parallel code from a validated Petri net model.

In our project, the code is generated from a validated model. There are many advantages :

- . The model is a formal description containing the engineering requirements.
- . The model has been verified and no design errors remain; The early detection of errors is justified from an economic point of view.
- . We can use the structural and behavioural properties, issued from the validation of the model, to optimize code generation.

In a Petri nets model, each object (place and token) can be seen in terms of an elementary task that synchronizes with other objects by means of transitions. The basic idea for an efficient implementation is to group together several non-concurrent elementary tasks in one sequential process, to minimize the synchronization.

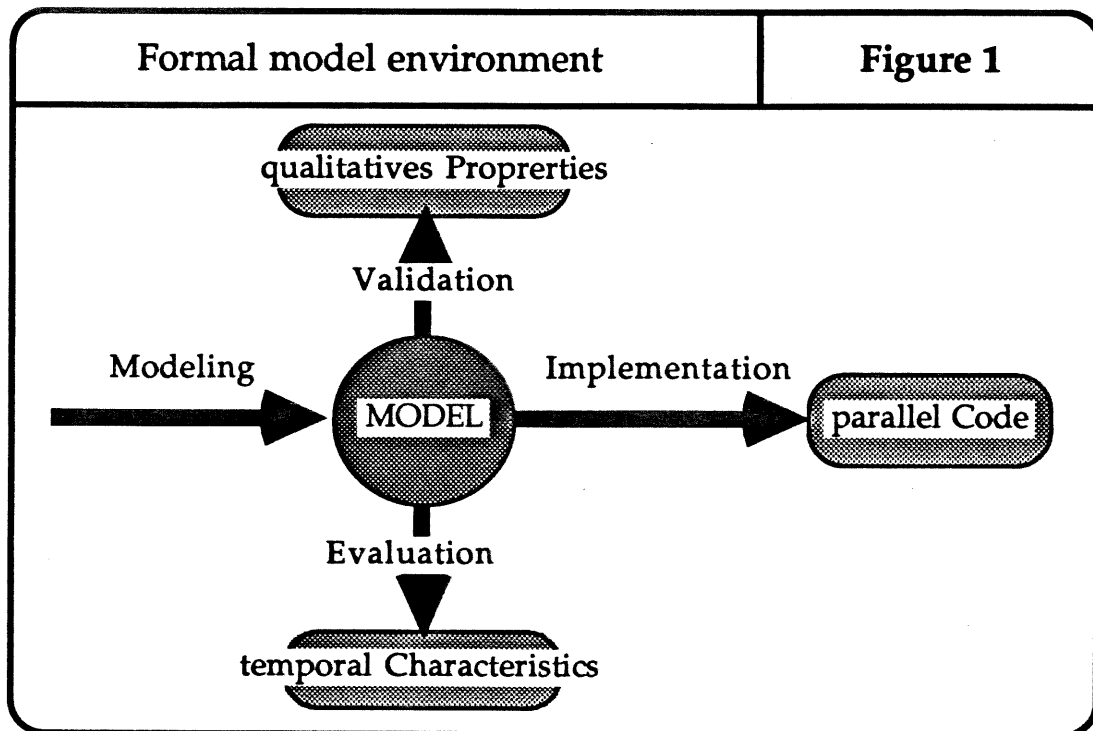
Among the high-level concurrent languages (ADA, OCCAM, CHILL, etc...), ADA has been chosen because it provides advanced tasking and structuring mechanisms, but we are only just beginning to study generation of OCCAM code for a multi-transputer system.

## 2. METHODOLOGY

### 2.1 The phases

From the specification of the system the **modeling** phase builds a model that describes all synchronizations (the precedence between tasks, the control access to global variables, communications, etc...) (Figure 1).

- . The **validation** phase enables the qualitative properties from the model to be obtained. This phase is useful to check the conception of the system [Cousin 87].
- . The **evaluation** phase constitutes the quantitative phase of the exploitation of the model. It checks the temporal characteristics of the system with the requirements.
- . The **implementation** phase is a natural continuation of the work done by the previous phases. The model (verified by the validation and evaluation phases) is used as a basic control scheme to generate the synchronisation code of the parallel system.



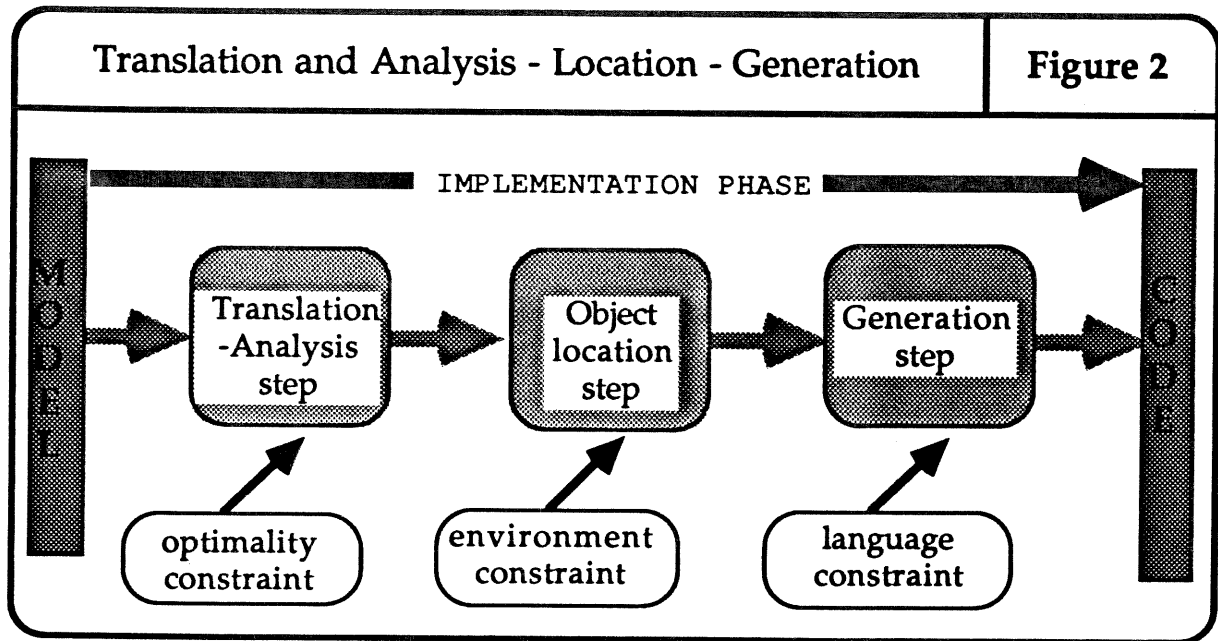
### 2.2 The steps

Our methodology organizes the implementation into 3 steps (translation and analysis, location, generation). These steps allow the progressive integration of the constraints respectively of the application, of the environment, and of the programming language, to meet the objectives (quality and performance criteria) (Figure 2).

Each step defines a set of new **objects** taking into account the constraints, using the objects defined by the previous step :

- . The first step is concerned with **semantics** and the internal synchronizations of the model. It performs the **Translation** and the **Analysis** of the validated model. The model is decomposed into a set of cooperating sequential processes which may be obtained from the analysis of the control structure of the model. Problems concerning conflicts need a careful consideration (deadlock, management of shared resources, etc...). This step produces a collection of objects needed for the next step.
- . The second step defines the object **location** for a specific distributed architecture. It manages the allocation of the hardware and software resources.

- . The third step generates the code. The semantic rules of Petri nets behaviour have to be expressed within the programming language. Moreover, new constraints may be added by the language itself.



For the Translation and Analysis step, we presented in a previous paper [Cousin 88], a technique tending towards an **optimal implementation** that minimizes the number of processes. The reduction minimizes the complexity of the synchronization needed to control the parallel system. Nevertheless this set of processes, supporting the execution of the parallel system, maintains the intrinsic parallelism of the model.

Rather than analyse the formal model to detect the optimal set, we reuse the **linear invariants** obtained from the validation phase of the model. An invariant is a conservative flow of the model which can be interpreted as the sequential states of a process. These invariants allow us to define the process distribution over the model, and then the optimal process number.

This Analysis of the model and the Location constraints of the second step enable the objects used by the generation step to be easily characterized. We determine in the following paragraph the types of the objects involved in the code generation.

### 3. APPLICATION

#### 3.1 The Objects

The following object types must be defined for the code generation. **State** objects are derived from the places of the Petri net model, while **Action** objects are derived from the transitions of the Petri net model. The distinction into subtypes is done by Analysis and Location steps, on the basis of model and architecture constraints: **process** or **resource** for the state objects, **process** or **synchronization** for action objects.

#### State

- . **Process** : models a possible state of a process.
  - . Simple : only one action is possible from this state.  
(at most one transition is potentially fireable from the place)
  - . Alternative : many actions are possible from this state.  
(more than one transition is potentially fireable from the place)

- . **Resource** : models a resource (data, message, record, ...)
  - . Private : exclusively accessed by a process.
  - . Shared : can be accessed by many processes.

### Action

- . **Process** : models an action to be performed by one process.
  - . Simple : no guard is associated with the execution of the action.  
(a guard is the condition for the existence of one or more resources)
  - . Guarded: a guard may prevent the execution of the action.
- . **Synchronization** : models an action which must be performed by cooperating processes in a synchronous way.
  - . Simple : no guard is associated with the action.
  - . Guarded: a guard may prevent the execution of the action.

## 3.2 The Model

We apply our method on a model which has been especially built to cover many technical problems and to include all the object types (Figure 3).

The model specifies three distributed processes {x, a, b}. We briefly describe their behaviour :

The process x, when all the conditions are satisfied (depending on marking of places **xPRL** and **PRG0**) prepares (transition **xTP3**) a message (Place **PRG7**) and informs both processes a and b.

The processes a and b have the same symmetric structure. So they compete in treating the message: one becomes the sender (transition **TP1**), the other becomes the receiver (transition **TP3**). Only one of them is allowed to send the message (transition **TP2**) to the other process which receives it (transition **TP4**).

Then, both processes synchronously (transition **abTS**) return to their home states (respectively places **aPP1** and **bPP1**). Then the same execution can be done again.

The figure 4 exhibits the type of each object obtained after the analysis and location steps. The places and transitions prefixed by a, b, or x belong to the associated process. The **PRGi** places are resource objects shared by several processes.

## 3.3 The Generation

The problematic of the generation phase is to use judiciously the target language and its specific objects. The similarity between the Petri net places and transitions and the ADA task and rendez-vous concepts make code production easier. Nevertheless a systematic translation from places and transitions to tasks and rendez-vous renders the code inefficient.

A close study of transition firing shows that it can be split into three operations :

- the precondition requires all the processes and the resources needed to execute the action.
- the action associated with the transition executes the processes on the resources .
- the postcondition releases all the processes and the resources used during the execution.

Our purpose is to reduce synchronization involved in the precondition and the postcondition of each transition. For example :

- a transition, linking two successive states of a same process, needs no precondition because the execution of an ADA task is obviously sequential.
- structures like "if or case" are simpler and more efficient than "rendez-vous" to synchronize elementary tasks of the same process.

Our code generator is written in ADA, has about 2800 lines of code, and uses packages intensively to facilitate the generic production of target code. The figure 5 shows the code produced from the application model by the generator. We can distinguish the code of the three ADA task associated with the three model processes.

#### 4. CONCLUSION

The objectives of the project PN\_TAGADA are to study the specific problems caused by the code generation from Petri net models, and the design of an automatic code generator.

The technical problems solved are :

- . the dissolving of the distinctive control of the Petri Nets model in ADA code,
- . the reduction of the processes number,
- . the resolution of distributed conflict,

to obtain an efficient code generator.

Code generation may be useful in rapid prototyping for two different purposes. The first is to show preliminary system properties to a customer without spending too much effort in the design process. The second is the evaluation of specific system properties in order to guarantee a suitable system design. In neither case can it be expected that a product system be the result of this process. However, in parallel with the prototype system parts of the system specification for the final product can be realized.

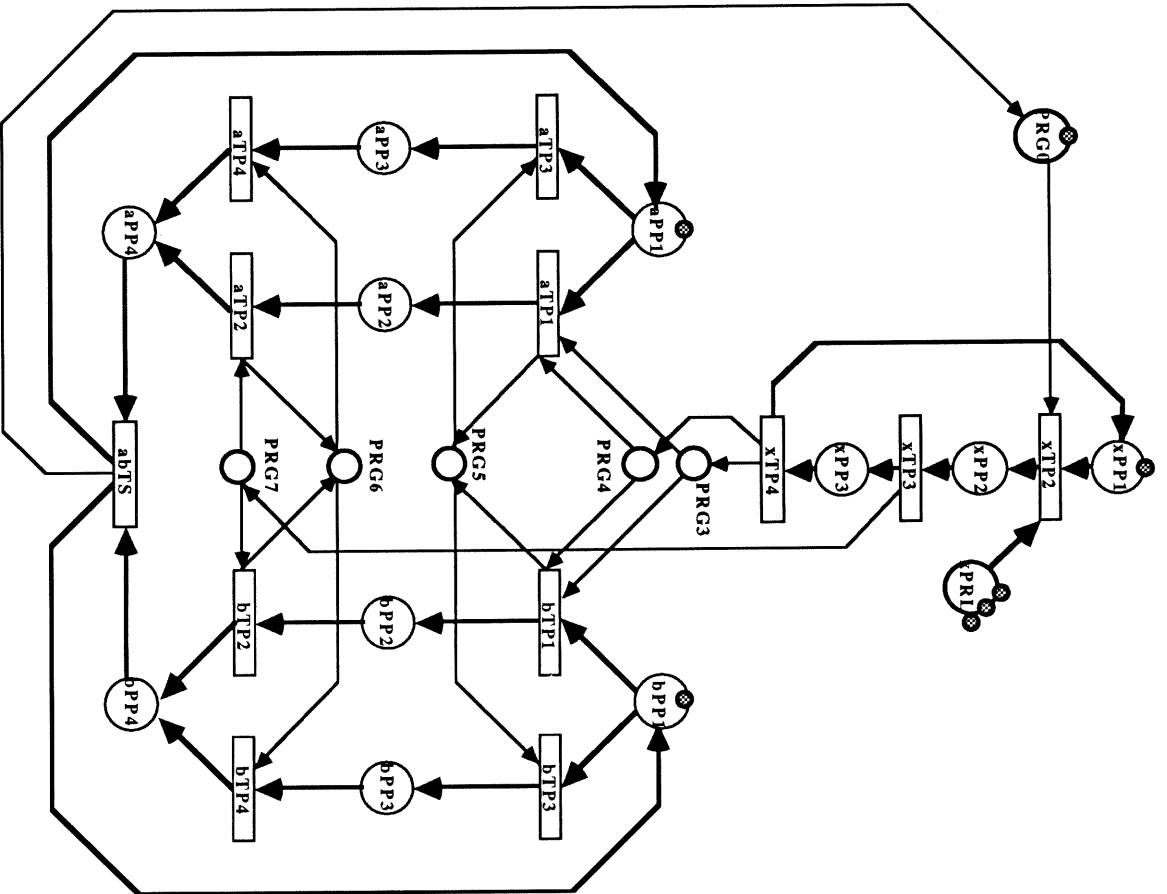
#### Acknowledgments

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- The Model - Figure 3

STATE	Processus	Simple	
		Private	Shared
Resource	Alternative	xPP1, xPP2, xPP3 aPP2, aPP3 bPP2, bPP3	PRG0, PRG3, PRG4 PRG5, PRG6, PRG7
		aPP1, aPP4 bPP1, bPP4	xPRL
ACTIONS	Processus	Simple	xTP3, xTP4
		Guarded	xTP2 aTP1, aTP2, aTP3, aTP4 bTP1, bTP2, bTP3, bTP4
	Synchrono- nization	Simple	
	Guarded	abTS	

The places (xPP1, aPP1, bPP1) contain one token, they are the initial states of respectively the x, a, b processes. The place (xPRL) contains three local resources, whereas place (PRG0) contains one global resource.

- Characterization of the Objects of the model - Figure 4



```

1211      g_list_loc := supprimer (g_list_loc);
1221      end loop;
1231      end if;
1241      if precondition
1251      then
1261          proc_B_TP3;
1271          etat := processus_B_B_TP4;
1281      else
1291          etat := processus_B_B_PPI;
1301      end if;
1311      -- Pas de code genere
1321      when processus_B_B_TP4 =>
1331          B_PP3 (Place Processus Simple)
1341          precondition := true;
1351          if precondition
1361          then
1371              g_list_loc := NULL;
1381              if gconsomme (PR66)
1391              then
1401                  g_list_loc := ajouter (PR66, g_list_loc);
1411              else
1421                  precondition := false;
1431              end if;
1441              while g_list_loc /= NULL loop
1451                  if not precondition
1461                  then
1471                      gproduire (contenu (g_list_loc));
1481                  end if;
1491                  g_list_loc := supprimer (g_list_loc);
1501              end loop;
1511          end if;
1521          proc_B_TP4;
1531          etat := processus_B_I_SYNC;
1541      else
1551          etat := processus_B_B_TP4;
1561      end if;
1571      -- Pas de code genere
1581      when others =>
1591          null; -- pour le compilateur ADA
1601      end case;
1611      end loop;
1621      end processus_B;
1631      task body processus_A is
1641          chr_A_PPI; tab_etat (1.. 2) := (1 => processus_A_TP3, 2 => processus_A_A_TP1);
1651          etat := naturel; continue (boolean := true; precondition := boolean; reponse := boolean; idon := boolean);
1661          cpt := naturel; g_list_loc := ptr_cg_pt_eli;
1671          begin
1681              accept aeq_init (init := naturel) do etat := init; end aeq_init;
1691              while continue loop
1701                  case etat is
1711                      when processus_A_I_SYNC =>
1721                          T_SYNC (Transition de Synchronisation Simple)
1731                          reponse := false;
1741                          while not (reponse) loop
1751                              T_SYNC.pret (IPPS, reponse);
1761                          end loop;
1771                          reponse := false;
1781                          while not (reponse) loop
1791                              T_SYNC.accuse (IPPS, reponse);
1801                          end loop;
1811          etat := processus_A_A_PPI;
1821          when processus_A_A_PPI =>
1831              -- A_PP1 (Place Processus Alternative)
1841              etat := tirage (chr_A_PPI);
1851          when processus_A_TP1 =>
1861              -- A_TP1 (Transition Processus Conditionnee)
1871              precondition := true;
1881              if precondition
1891              then
1901                  g_list_loc := NULL;
1911                  if gconsomme (PR64)
1921                  then
1931                      g_list_loc := ajouter (PR64, g_list_loc);
1941                  else
1951                      precondition := false;
1961                  end if;
1971                  if gconsomme (PR63)
1981                  then
1991                      g_list_loc := ajouter (PR63, g_list_loc);
2001                  else
2011                      precondition := false;
2021                  end if;
2031                  while g_list_loc /= NULL loop
2041                      if not precondition
2051                      then
2061                          gproduire (contenu (g_list_loc));
2071                      end if;
2081                      g_list_loc := supprimer (g_list_loc);
2091                  end loop;
2101              if precondition
2111              then
2121                  proc_A_TP1;
2131                  etat := processus_A_A_TP2;
2141                  gproduire (PR65);
2151              else
2161                  etat := processus_A_A_PPI;
2171              end if;
2181          when processus_A_A_TP2 =>
2191              -- A_TP2 (Transition Processus Conditionnee)
2201              precondition := true;
2211              if precondition
2221              then
2231                  g_list_loc := NULL;
2241                  if gconsomme (PR67)
2251                  then
2261                      g_list_loc := ajouter (PR67, g_list_loc);
2271                  else
2281                      precondition := false;
2291                  end if;
2301                  while g_list_loc /= NULL loop
2311                      if not precondition
2321                      then
2331                          gproduire (contenu (g_list_loc));
2341                      end if;
2351                      g_list_loc := supprimer (g_list_loc);
2361                  end loop;
2371              if precondition
2381              then
2391                  proc_A_TP2;
2401                  gproduire (PR66);

```

```

241:   etat := processus_A_I_SYNC;
242:   else
243:   etat := processus_A_TP2;
244:   end if;
245:   when processus_A_TP3 => -- A_TP3 (Transition Processus Conditionnee)
246:   precondition := true;
247:   if precondition
248:   then
249:   g_list_loc := NULL;
250:   if gconsole (PR65)
251:   then
252:   g_list_loc := ajouter (PR65, g_list_loc);
253:   else
254:   precondition := false;
255:   end if;
256:   while g_list_loc /= NULL loop
257:   if not precondition
258:   then
259:   gproduire (contenu (g_list_loc));
260:   end if;
261:   g_list_loc := supprimer (g_list_loc);
262:   end loop;
263:   end if;
264:   if precondition
265:   then
266:   proc A_TP3;
267:   etat := processus_A_TP4;
268:   else
269:   etat := processus_A_PPI;
270:   end if;
271:   -- Pas de code genere
272:   when processus_A_TP4 => -- A_TP4 (Transition Processus Conditionnee)
273:   precondition := true;
274:   if precondition
275:   then
276:   g_list_loc := NULL;
277:   if gconsole (PR66)
278:   then
279:   g_list_loc := ajouter (PR66, g_list_loc);
280:   else
281:   precondition := false;
282:   end if;
283:   while g_list_loc /= NULL loop
284:   if not precondition
285:   then
286:   gproduire (contenu (g_list_loc));
287:   end if;
288:   g_list_loc := supprimer (g_list_loc);
289:   end loop;
290:   end if;
291:   proc A_TP4;
292:   etat := processus_A_I_SYNC;
293:   else
294:   etat := processus_A_TP4;
295:   end if;
296:   when others =>
297:   null; -- pour le compilateur ADA
298:   -- Pas de code genere
299:   end loop;
300:

```

```

301:   end case;
302:   end loop;
303:   end processus_A;
304:   -- /processus: processus_X
305:   task body processus_X is
306:   type r1_processus_X is (X_PRL);
307:   package pr1_processus_X is new ress_loc (r1_processus_X);
308:   use pr1_processus_X;
309:   package ptr_r1_processus_X is new gestist (r1_processus_X);
310:   use ptr_r1_processus_X;
311:   etat : natural; continue boolean := true; precondition: boolean; reponser: boolean; bidon : boolean;
312:   cpt : natural; list_loc: ptr_r1_processus_X; pt_elt: ptr_r1_processus_X; ptr_rg_pt_elt;
313:   begin
314:   lproduire (X_PRL); lproduire (X_PRL); lproduire (X_PRL); -- Marquee initial des ressources locales
315:   accept marq_init (limit sin natural) do etat := init; end marq_init;
316:   while continue loop
317:   case etat is
318:   when processus_X_X_TP2 => -- X_TP2 (Transition Processus Conditionnee)
319:   precondition := true;
320:   lconsole (X_PRL);
321:   if precondition
322:   then
323:   g_list_loc := NULL;
324:   if gconsole (PR68)
325:   then
326:   g_list_loc := ajouter (PR68, g_list_loc);
327:   else
328:   precondition := false;
329:   end if;
330:   while g_list_loc /= NULL loop
331:   if not precondition
332:   then
333:   gproduire (contenu (g_list_loc));
334:   end loop;
335:   end if;
336:   if precondition
337:   then
338:   proc X_TP2;
339:   etat := processus_X_X_TP3;
340:   else
341:   lproduire (X_PRL);
342:   etat := processus_X_X_TP2;
343:   end if;
344:   -- Pas de code genere
345:   when processus_X_X_TP3 => -- X_TP3 (Transition Processus Simple)
346:   proc X_TP3;
347:   gproduire (PR67);
348:   etat := processus_X_X_TP4;
349:   -- X_PP3 (Transition Processus Simple)
350:   when processus_X_X_TP4 => -- X_TP4 (Transition Processus Simple)
351:   proc X_TP4;
352:   gproduire (PR64);
353:   gproduire (PR63);
354:   etat := processus_X_X_TP2;
355:   -- X_PPI (Transition Processus Simple)
356:   when others =>
357:   null; -- pour le compilateur ADA
358:   end case;
359:   end loop;
360:

```

```

3611 end processus_xj
3621 task body T_SYNC is -- Code de la tache implementant la transition T_SYNC (I/Transition de Synchronisation Simple)
3631 maxpps i constant := 2; maxppa i constant := 8; pps i natural := 8; ppa i natural := 8; active i boolean := false;
3641 begin -- tache transition
3651 loop
3661 while not (active) loop
3671 delay 0.0; -- provoque une election
3681 select
3691 accept pret (t_precond in tplace) reponse tout boolean do
3701 case t_precond is
3711 when IPPA =>
3721 ppa := ppa + 1;
3731 when others =>
3741 pps := pps + 1;
3751 end case;
3761 if (pps = maxpps) AND (ppa = maxppa)
3771 then
3781 active := true;
3791 end if;
3801 reponse := true;
3811 end pret;
3821 or
3831 accept accuse (t_precond in tplace) reponse tout boolean do
3841 if t_precond = IPPA
3851 then
3861 ppa := ppa - 1;
3871 end if;
3881 reponse := false;
3891 end accuse;
3901 end select;
3911 end loop;
3921 proc T_SYNC;
3931 produire (PR68);
3941 while (pps > 0) or (pps > 0) loop
3951 select
3961 accept pret (t_precond in tplace) reponse tout boolean do
3971 reponse := false;
3981 end pret;
3991 or
4001 accept accuse (t_precond in tplace) reponse tout boolean do
4011 case t_precond is
4021 when IPPA =>
4031 ppa := ppa - 1;
4041 when others =>
4051 pps := pps - 1;
4061 end case;
4071 reponse := true;
4081 end accuse;
4091 end select;
4101 end loop;
4111 active := false;
4121 end loop;
4131 end T_SYNC;
4141 begin -- PARTIR
4151 aleatoire.init(max_att := 5);
4161 produire (PR68);
4171 processus_B.marq_init (1);
4181 processus_A.marq_init (1);
4191 processus_X.marq_init (1);
4201 end PARTIR;

```



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