

# Simulation of effective subshifts by two-dimensional SFT

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# Tilings as dynamical systems

Let  $\mathcal{A}$  be a finite alphabet and consider the grid  $\mathbb{Z}^d$ .

The set  $\mathcal{A}^{\mathbb{Z}^d}$  endowed by the product topology is compact and  $\mathbb{Z}^d$  acts by shift on  $\mathcal{A}^{\mathbb{Z}^d}$ :

$$\forall x \in \mathcal{A}^{\mathbb{Z}^d} \text{ and } \forall n, i \in \mathbb{Z}^d, \sigma^n(x)_i = x_{i+n}$$

$$\mathcal{A} = \{ \text{red square}, \text{blue square} \}$$

The diagram shows the full shift  $\sigma^{(1,2)}$  on a 2D grid of red and blue squares. The left grid is shifted by  $(1,2)$  to produce the right grid. The central cell in both grids is labeled '0'.

The dynamical system  $(\mathcal{A}^{\mathbb{Z}^d}, \sigma)$  is called the *full shift*.

Let  $\mathbf{T} \subset \mathcal{A}^{\mathbb{Z}^d}$  be a closed  $\sigma$ -invariant subset. The dynamical system  $(\mathbf{T}, \sigma)$  is called a *subshift*.

# Subshifts defined by forbidden patterns

For a finite subset  $\mathbb{U} \subset \mathbb{Z}^d$  we can consider finite pattern  $u \in \mathcal{A}^{\mathbb{U}}$ .

Let  $F$  be a set of patterns, we define the subshift where the forbidden patterns are  $F$ :

$$\mathbf{T}_{\mathcal{A},F} = \{x \in \mathcal{A}^{\mathbb{Z}^d} / \forall p \in F, p \text{ does not appear in } x\} \subseteq \mathcal{A}^{\mathbb{Z}^d}$$

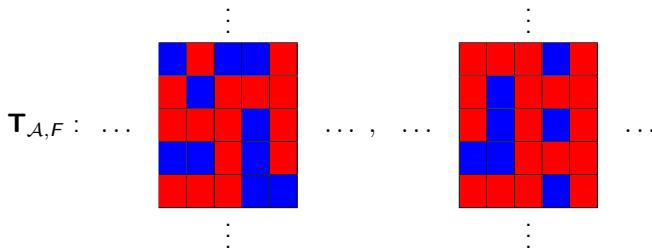
## Some class of subshifts:

- **T** *fullshift* ( $\mathbf{T} \in \mathcal{FS}$ )  $\Leftrightarrow \Sigma = \mathbf{T}_F = \mathcal{A}^{\mathbb{Z}^d}, F = \emptyset$
- **T** *subshift of finite type* ( $\mathbf{T} \in \mathcal{SFT}$ )  $\Leftrightarrow \exists F$  finite set of patterns such that,  $\mathbf{T} = \mathbf{T}_F$
- **T** *effective subshift* ( $\mathbf{T} \in \mathcal{RE}$ )  $\Leftrightarrow \exists F$  recursive enumerable set of patterns such that  $\Sigma = \mathbf{T}_F$ .

## Example of SFT of dimension 2

$$\mathcal{A} = \{ \text{red square}, \text{blue square} \}$$

$$F = \left\{ \begin{array}{|c|c|} \hline \text{red} & \text{red} \\ \hline \text{red} & \text{red} \\ \hline \end{array}, \begin{array}{|c|c|} \hline \text{blue} & \text{blue} \\ \hline \text{blue} & \text{blue} \\ \hline \end{array} \right\}$$





# Operations on subshifts, simulation

$\mathcal{S}$ : set of all subshifts (all dimensions, all finite alphabets)

- *Operations* on subshifts:

- ▶  $op : \mathcal{S} \rightarrow \mathcal{S}$

- ▶ or  $op : \mathcal{S} \times \mathcal{S} \rightarrow \mathcal{S}$

- *Closure* of a class of subshifts  $\mathcal{U} \subset \mathcal{S}$  by a set of operations  $Op$ :

$Cl_{Op}(\mathcal{U})$ : smallest subset of  $\mathcal{S}$  stable by  $Op$  which contains  $\mathcal{U}$ .

- $\mathbf{T}$  *simule*  $\mathbf{T}'$  by  $Op$  if  $\mathbf{T}' \in Cl_{Op}(\mathbf{T})$  (notation :  $\mathbf{T}' \leq_{Op} \mathbf{T}$ ).

$$Cl_{Op}(\mathbf{T}) = \{\mathbf{T}' : \mathbf{T}' \leq_{Op} \mathbf{T}\}.$$

# Product operation: **Prod**

## Definition

Let  $\mathbf{T}_i \subseteq \mathcal{A}_i^{\mathbb{Z}^d}$  for any  $i \in [1, n]$  be  $n$  subshifts of the same dimension, define:

$$\mathbf{Prod}(\mathbf{T}_1, \dots, \mathbf{T}_n) = \mathbf{T}_1 \times \dots \times \mathbf{T}_n \subseteq (\mathcal{A}_1 \times \dots \times \mathcal{A}_n)^{\mathbb{Z}^d}.$$

$$\left. \begin{array}{l} \Sigma = \mathbf{T}_F \subseteq \{a, b, c\}^{\mathbb{Z}^2} \\ F = \left\{ \begin{array}{|c|c|} \hline * & a \\ \hline a & * \\ \hline \end{array}, \begin{array}{|c|c|} \hline * & b \\ \hline b & * \\ \hline \end{array}, \begin{array}{|c|c|} \hline * & c \\ \hline c & * \\ \hline \end{array} \right\} \\ \Sigma' = \mathbf{T}_{F'} \subseteq \{\text{red}, \text{blue}\}^{\mathbb{Z}^2} \\ F' = \left\{ \begin{array}{|c|c|} \hline \text{red} & \text{blue} \\ \hline \text{blue} & \text{red} \\ \hline \end{array} \right\} \end{array} \right\} \Rightarrow \begin{array}{l} \Sigma \times \Sigma' \subseteq \{a, b, c, a, b, c\}^{\mathbb{Z}^2} \\ F \times \{\text{red}, \text{blue}\}^{\cup} \cup \{a, b, c\}^{\cup} \times F' \\ \left\{ \begin{array}{|c|c|} \hline * & a \\ \hline a & * \\ \hline \end{array}, \begin{array}{|c|c|} \hline * & a \\ \hline a & * \\ \hline \end{array}, \begin{array}{|c|c|} \hline * & a \\ \hline a & * \\ \hline \end{array}, \dots \right\} \end{array}$$

**Remark :** One has  $\mathcal{C}l_{\mathbf{Prod}}(\mathcal{FS}) = \mathcal{FS}$  and  $\mathcal{C}l_{\mathbf{Prod}}(\mathcal{SFT}) = \mathcal{SFT}$ .

## Finite Type operation: **FT**

### Définition

Let  $\mathbf{T} \in \mathcal{S}$ , there exists  $F'$  a family of pattern such that  $\mathbf{T} = \mathbf{T}_{F'}$ .  
For a finite family  $F$  of pattern, define

$$\mathbf{FT}_F(\mathbf{T}) = \mathbf{T}_{F \cup F'}.$$



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**Remark :** By definition, one has:

$$\mathcal{Cl}_{\mathbf{FT}}(\mathcal{FS}) = \mathcal{SFT}$$

# Factor operation: **Fact**

## Definition

Let  $\mathbf{T} \subseteq \mathcal{A}^{\mathbb{Z}^d}$  be a subshift and let  $\pi : \mathcal{A}^{\mathbb{Z}^d} \rightarrow \mathcal{B}^{\mathbb{Z}^d}$  be a morphism (continuous and  $\sigma \circ \pi = \pi \circ \sigma$ ),  $\mathbf{Fact}_\pi(\mathbf{T}) = \pi(\mathbf{T}) \subseteq \mathcal{B}^{\mathbb{Z}^d}$  is a factor of  $\mathbf{T}$ .

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## Example :

$\mathcal{A} = \{0, 1, 2\}$  et  $\Sigma \subseteq \mathcal{A}^{\mathbb{Z}}$

$\Sigma = \mathbf{T}_{\{00,22,01,12\}}$  et  $\pi(0) = \pi(2) = 0, \pi(1) = 1$

$\Rightarrow \pi(\Sigma) = \{x \in \{0, 1\}^{\mathbb{Z}} / \text{blocks of 0 have even length}\} = \mathbf{T}_{\{0,1\}, \{10^{2n+1}1 : n \in \mathbb{N}\}}$

**Remark :**  $SFT \subsetneq Cl_F(SFT)$ .

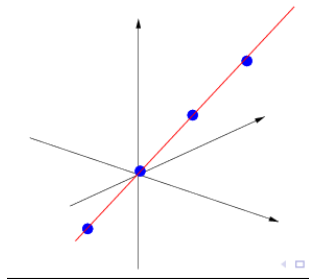
By definition,  $Cl_F(SFT)$  is the class of *sofic subshifts*. In dimension 1, it is possible to characterize sofic subshift as subshifts with regular forbidden patterns.

# Projective Subaction: SA

## Definition

Let  $\mathbb{G}$  be a sub-group of  $\mathbb{Z}^d$  finitely generated by  $u_1, u_2, \dots, u_{d'}$  ( $d' \leq d$ ). Let  $\mathbf{T} \subseteq \mathcal{A}^{\mathbb{Z}^d}$  be a subshift :

$$\mathbf{SA}_{\mathbb{G}}(\mathbf{T}) = \left\{ y \in \mathcal{A}^{\mathbb{Z}^d} : \exists x \in \mathbf{T} \text{ such that } \forall i_1, \dots, i_{d'} \in \mathbb{Z}^{d'}, \right. \\ \left. y_{i_1, \dots, i_{d'}} = x_{i_1 u_1 + \dots + i_{d'} u_{d'}} \right\}.$$



## Example of projective subaction

Let  $\mathcal{A} = \{0, 1, 2, 3, 4, a, b\}$ , it is possible to define a SFT  $\mathbf{T} \subset \mathcal{A}^{\mathbb{Z}^2}$  such that 0 is a background and finite non 0composant have the following form:

0	0	0	0	0	0	0	0
0	*	1	...	...	1	b	0
0	4	...	1	1	...	2	0
0	...	4	*	b	2	...	0
0	...	4	a	*	2	...	0
0	4	...	3	3	...	2	0
0	a	3	...	...	3	*	0
0	0	0	0	0	0	0	0

Let  $\mathbb{G} = \{(i, i) : i \in \mathbb{Z}\}$ , we have:

$$\mathbf{SA}_{\mathbb{G}}(\mathbf{T}) = \mathbf{T}_{\{*a^n b^m * : n \neq m\}} \notin \text{Sofic}.$$

### Proposition

$$\mathcal{C}_{\text{SA}}(\mathcal{RE}) = \mathcal{RE}$$

$$\text{In particular } \mathcal{C}_{\text{SA}}(\text{Sofic}) = \mathcal{C}_{\text{Fact, SA}}(\text{SFT}) \subset \mathcal{RE}$$

# Main result

## Theorem (Hochman)

Every effective subshifts of dimension  $d$  can be obtained using **SA** and **Fact** on a SFT of dimension  $d + 2$ .

$$\mathcal{C}l_{\text{Fact,SA}}(\mathcal{SFT} \cap \mathcal{S}_{d+2}) \cap \mathcal{S}_{\leq d} = \mathcal{RE} \cap \mathcal{S}_{\leq d}$$

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## Theorem (Aubrun & S. or Durand & Romashchenko & Shen)

Every effective subshifts of dimension  $d$  can be obtained using **SA** and **Fact** on a SFT of dimension  $d + 1$ .

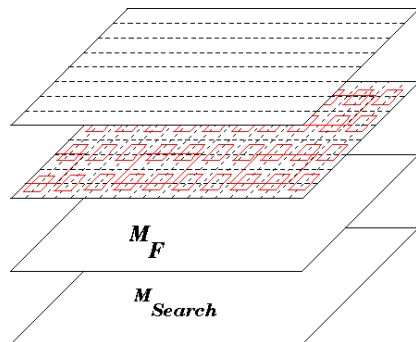
$$\mathcal{C}|_{\text{Fact,SA}}(\text{SFT} \cap \mathcal{S}_{d+1}) \cap \mathcal{S}_{\leq d} = \mathcal{RE} \cap \mathcal{S}_{\leq d}$$

## Four layers

We want to simulate an effective subshift  $\Sigma \subseteq \mathcal{A}_\Sigma^{\mathbb{Z}^2}$  with a SFT of dimension 2 (it is easy to generalize to other dimensions).

### Different layers:

- **Layer 1:** a superposition of configuration  $x \in \mathcal{A}_\Sigma^{\mathbb{Z}^2}$  (a candidate  $x \in \Sigma$ ?),
- **Layer 2:** computation zones used by  $\mathcal{M}_{\text{Forbid}}$  et  $\mathcal{M}_{\text{Search}}$  equipped with a clock,
- **Layer 3:** Turing machine  $\mathcal{M}_{\text{Forbid}}$  enumerates forbidden patterns,
- **Layer 4:** Turing machine  $\mathcal{M}_{\text{Search}}$  checks the configuration  $x$ .





## Layer 1: the candidate $x \in \Sigma^*$ ?

We align all letters of the first layer to obtain the same configuration horizontally.

Finite condition:

$$\mathbf{Align} = \left\{ \begin{array}{|c|} \hline a \\ \hline b \\ \hline \end{array}, a \neq b \in \mathcal{A}_\Sigma \right\}$$

The first layer is constituted by:

$$\mathbf{T}_{\mathbf{Align}} = \mathbf{FT}_{\mathbf{Align}} \left( \mathcal{A}_\Sigma^{\mathbb{Z}^2} \right)$$

**Aim:**

We want to eliminate each  $x$  which contains **forbidden patterns** of  $\Sigma$ .

# We want to code a Turing machine with a SFT

## Definition: Turing machine

A *Turing machine* is  $\mathcal{M} = (Q, \Gamma, \#, q_0, \delta, Q_F)$  with:

- $Q$  finite set of states;  $q_0 \in Q$  initial state;
- $\Gamma$  finite alphabet;
- $\# \notin \Gamma$  white symbol
- $\delta : Q \times \Gamma \rightarrow Q \times \Gamma \times \{\leftarrow, \cdot, \rightarrow\}$  function of transition;
- $F \subset Q_F$  set of final states.

The rule  $\delta(q_1, x) = (q_2, y, \leftarrow)$  is coded by:

$(q_2, z)$	$y$	$z'$
$z$	$(q_1, x)$	$z'$

It is possible to consider the SFT  $\mathbf{T}_{\mathcal{M}}$  for a Turing machine  $\mathcal{M}$

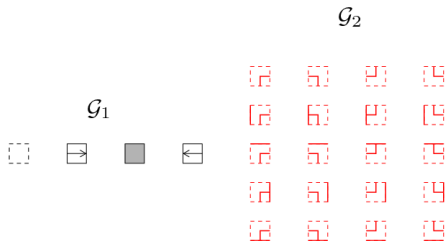
## Problem

How initialize the computation?

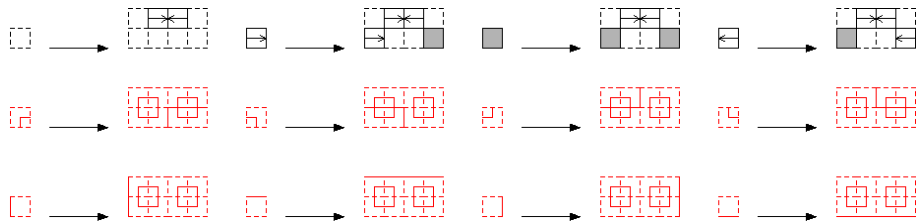


## Layer 2: the grid

The alphabets  $\mathcal{G}_1 \times \mathcal{G}_2$  on which the substitution is defined

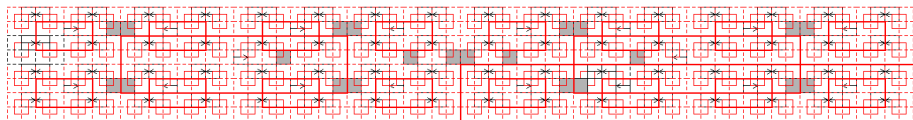
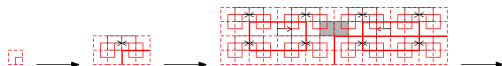


Substitution rules:



## Layer 2: the grid

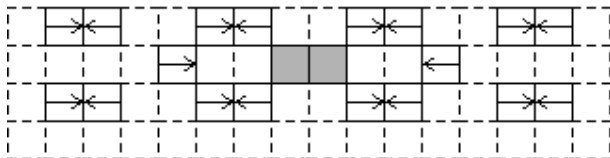
Four iterations of the substitution  $s_{\text{Grid}}$ :



By the result of Mozes, the fixe point obtained generates a sofic denoted  $\mathbf{T}_{\text{Grid}}$ .

# Description of computation zones

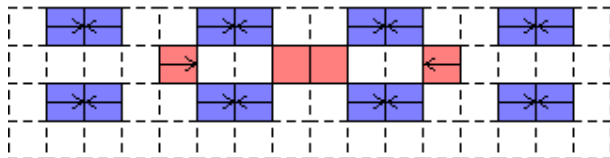
We just consider the projection on  $\mathcal{G}_1$ .



- : tile of communication
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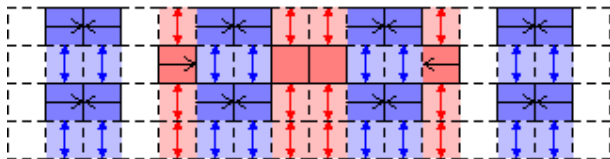
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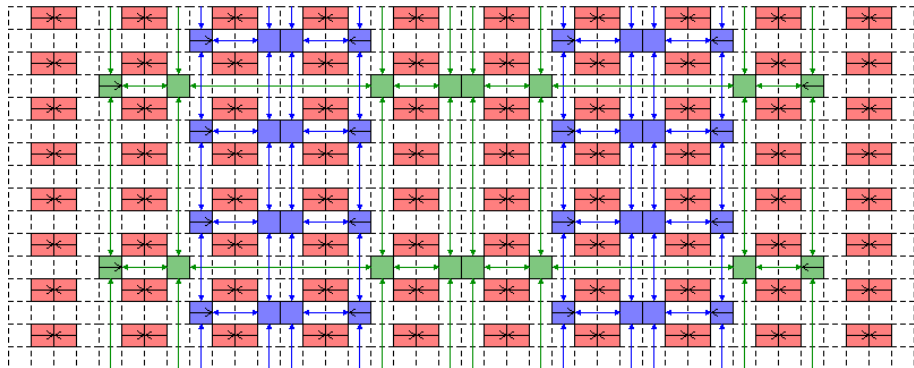


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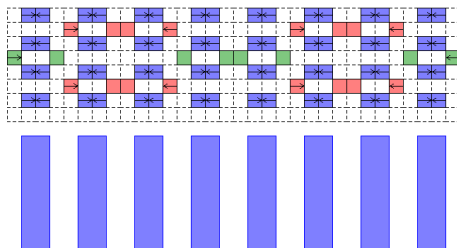
# Description of computation zones

And more generally:



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We have fractionated computation strips of different level (level 1, level 2, level 3):

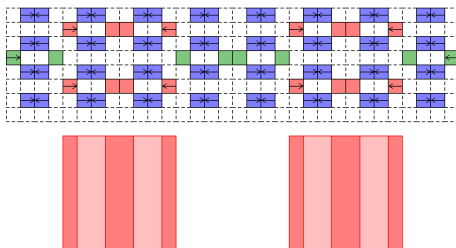


A computation strip of level  $n$  has the following properties :

- the width is  $2^n$ ,
- each rows have computation boxes of the same level,
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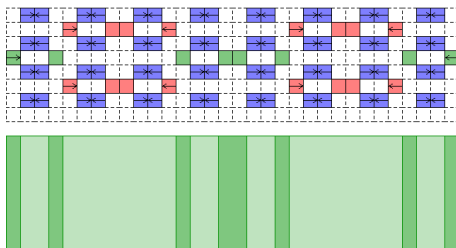


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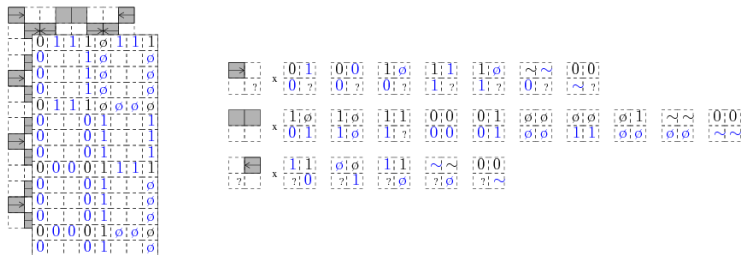


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## Layer 2: A grid and a clock

To initialize the computation we code a clock by finite rules:



The layer 2 can be defined as:

$$\mathbf{T}_{\text{Clock}} = \mathbf{FT}_{\text{Count} \cup \text{Consist} \cup \text{Synchro}} \left( \mathbf{Prod} \left( \mathbf{T}_{\text{Grid}}, \mathcal{C}^{\mathbb{Z}^2} \right) \right)$$

For a strip of level  $n$ , this allows to initialize computation every  $2^{2^n}$ .

# How to simulate a Turing machine with $\mathbf{T}_{\text{clock}}$

We use the operation **FT** on **Prod** ( $\mathbf{T}_{\text{clock}}, \mathcal{A}_{\mathcal{M}}^2$ ) to add computation of  $\mathcal{M}$  in the strips:

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For a Turing machine  $\mathcal{M}$ , one can consider:

$$\mathbf{T}_{\mathcal{M}} = \mathbf{FT}_{\mathbf{Work}_{\mathcal{M}}} \left( \mathbf{Prod} \left( \mathbf{T}_{\text{Grid}}, \mathcal{A}_{\mathcal{M}}^{\mathbb{Z}^2} \right) \right)$$

where  $\mathbf{Work}_{\mathcal{M}} = \mathbf{Transfer} \cup \mathbf{Init} \cup \mathbf{Comp} \cup \mathbf{Bound}$ .

# How to simulate a Turing machine with $T_{\text{Clock}}$

↑	a	(q <sub>b+</sub> , #)	↑	↑	a	(q <sub>b+</sub> , #)	↑	↑	a	(q <sub>b+</sub> , #)	↑	↑	a
↑	↑	↑	↑	a	↕	↕	b	(q <sub>  </sub> , #)	↕	↕	#	↑	↑
↑	a	(q <sub>b+</sub> , #)	↑	↑	a	(q <sub>b+</sub> , #)	↑	↑	a	(q <sub>b+</sub> , #)	↑	↑	a
a	↕	↕	(q <sub>b+</sub> , #)	↕	↕	↕	↕	↕	↕	↕	↕	#	↕
↑	a	(q <sub>b+</sub> , #)	↑	↑	a	(q <sub>b+</sub> , #)	↑	↑	a	(q <sub>b+</sub> , #)	↑	↑	a
↑	↑	↑	↑	a	↕	↕	b	(q <sub>  </sub> , #)	↕	↕	#	↑	↑
↑	a	(q <sub>b+</sub> , #)	↑	↑	a	(q <sub>b+</sub> , #)	↑	↑	a	(q <sub>b+</sub> , #)	↑	↑	a
↑	↑	↑	↑	↑	↑	↑	↑	↑	↑	↑	↑	↑	↑
↑	a	(q <sub>b+</sub> , #)	↑	↑	a	(q <sub>b+</sub> , #)	↑	↑	a	(q <sub>b+</sub> , #)	↑	↑	a
↑	↑	↑	↑	a	↕	↕	(q <sub>b+</sub> , #)	#	↕	↕	#	↑	↑
↑	(q <sub>0</sub> , #)	#	↑		(q <sub>0</sub> , #)	#			(q <sub>0</sub> , #)	#	↑	↑	(q <sub>0</sub> , #)
(q <sub>0</sub> , #)	↕	↕	#	↕	↕	↕	↕	↕	↕	↕	↕	#	↕

## Layer 3: Detection of forbidden patterns by $\mathcal{M}_{\text{Forbid}}$

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Zone de responsabilité de  $\mathcal{M}_{\text{Forbid}}$



$a_0$	$a_1$	$a_2$	$\dots$	$\dots$	$\dots$	$\dots$	$a_N$
-------	-------	-------	---------	---------	---------	---------	-------

$f_0$	$f_1$	$f_2$	$\dots$
-------	-------	-------	---------

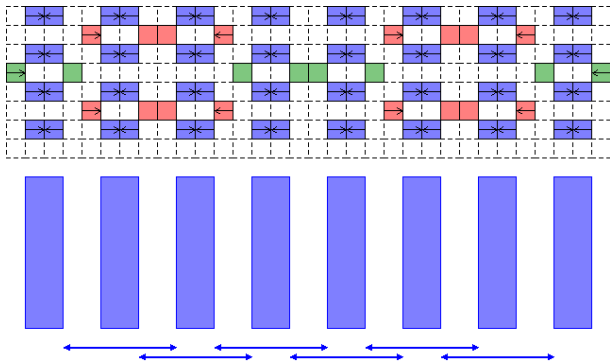
$f_0$	$f_1$	$f_2$	$\dots$
-------	-------	-------	---------

$f_0$	$f_1$	$f_2$	$\dots$
-------	-------	-------	---------

- to obtain the value in the layer 1 of  $a_k$ ,  $\mathcal{M}_{\text{Forbid}}$  need the help of  $\mathcal{M}_{\text{Search}}$ :  
 $\mathcal{M}_{\text{Forbid}}$  gives the address  $k$  and receive  $a_k$

# Responsibility zones of $\mathcal{M}_{\text{Forbid}}$

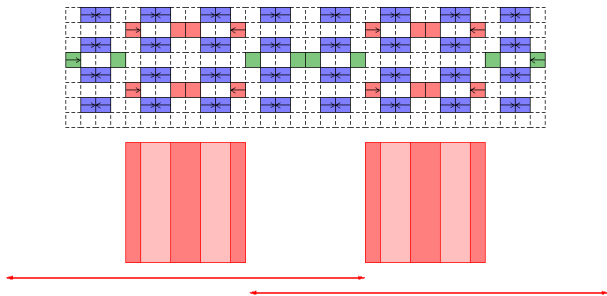
Responsibility zones must scan all the configuration considered, thus responsibility zones of same level overlap ( $\dots x_{-2}x_{-1}x_0 \in \mathcal{L}(\Sigma)$  and  $x_0x_1x_2 \dots \in \mathcal{L}(\Sigma)$ ) does not imply that  $\dots x_{-2}x_{-1}x_0x_1x_2 \dots \in \mathcal{L}(\Sigma)$ ).



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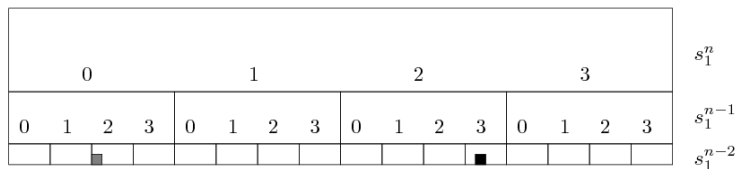
The Turing machine  $\mathcal{M}_{\text{Forbid}}$  of a level  $n$  can ask at  $\mathcal{M}_{\text{Search}}$  of the same level or neighbor  $\mathcal{M}_{\text{Search}}$  of the same level.



## Layer 4: The Turing machine $\mathcal{M}_{\text{Search}}$

We want to construct a Turing machine  $\mathcal{M}_{\text{Search}}$  which can communicate with different levels in view to explore all the configuration checked.

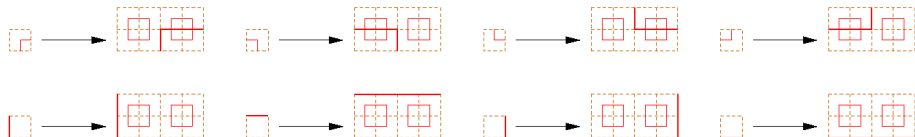
When you give a strip it is possible to give an address of each boxes in function of the place in a de-substitute pattern:



The black box address is 231 and the grey box address is 020.

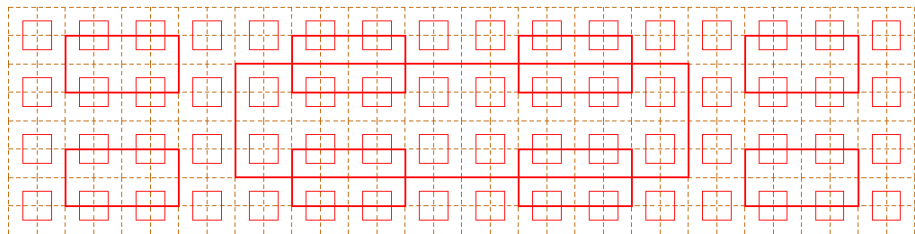
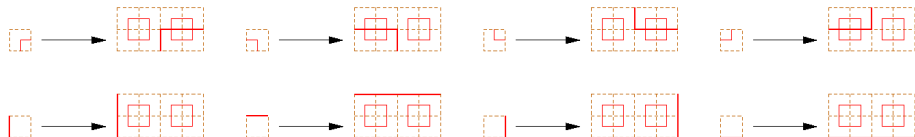
# Communication between $\mathcal{M}_{\text{Search}}$ of different level

With the alphabet  $\mathcal{G}_2$ , we construct channels of communication:



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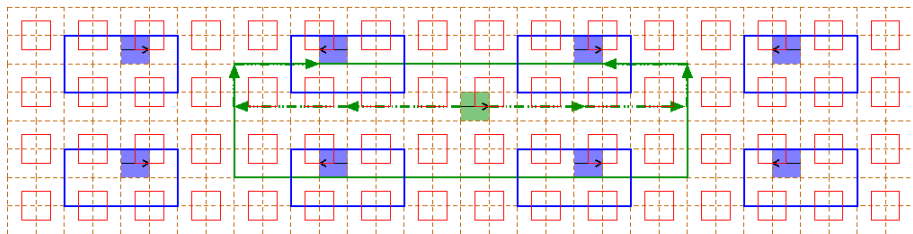
With the alphabet  $\mathcal{G}_2$ , we construct channels of communication:



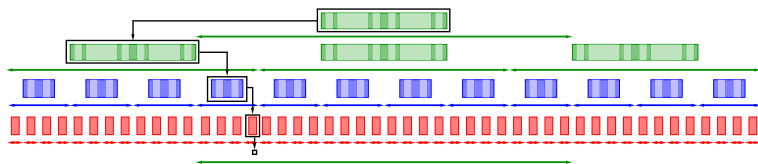
# Communication between $\mathcal{M}_{\text{Search}}$ of different level

Principle :

- each border of a computation zone ( $\square \rightarrow$  or  $\leftarrow \square$ ) is in the center of a rectangle of level  $n$ ;
- for each rectangle of level  $n$ , there is in connection only with  $\square \rightarrow$  and  $\leftarrow \square$  of two Turing machines of level  $n - 1$

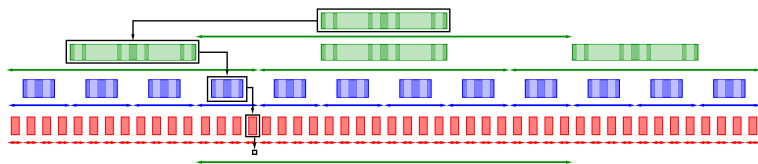


$\mathcal{M}_{\text{Search}}$  holds



- Each  $\mathcal{M}_{\text{Search}}$  has enough space to code address:
  - ▶ the size of computation zone of level  $n$  is  $2^n$ ,
  - ▶ the size of a responsibility zone of level  $n$  is  $6 \times 4^{n-1}$ ,
  - ▶ with an alphabet of cardinality 4, we just need  $n$  bits.

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  - ▶ with an alphabet of cardinality 4, we just need  $n$  bits.
- Each  $\mathcal{M}_{\text{Search}}$  can calculate for a given  $\mathcal{M}_{\text{Forbid}}$ :
  - ▶ let  $t(n)$  be the time taken by  $\mathcal{M}_{\text{Search}}$  to give an answer to a Turing machine  $\mathcal{M}_{\text{Forbid}}$  of order  $n$ . One has

$$t(n) \leq n \times 2^n + 4 \times t(n-1)$$

So  $t(n) \leq 2^n \times \mathcal{O}(n^2 2^n)$ .

- ▶ a clock of level  $n$  is initialised every  $2^{2^n}$
- ▶ the time of answer is "absorbed" by the exponential time of the clock.

# The final construction

- condition **Request** :  $\mathcal{M}_F$  ask  $\mathcal{M}_{\text{Search}}$  the value of a box in the respnsability zone and wait the answer
- condition **Forbid** : we exclude the configuration when  $\mathcal{M}_{\text{Forbid}}$  encounter a forbidden pattern

$$\mathbf{T}_{\text{Final}} = \mathbf{FT}_{\text{Work}_{\mathcal{M}_{\text{Request}}}} \cup \mathbf{Work}_{\mathcal{M}_{\text{Search}}} \cup \mathbf{Com} \cup \mathbf{Forbid} \left( \mathbf{T}_{\text{Layer}} \right) .$$

where

$$\mathbf{T}_{\text{Layer}} = \mathbf{Prod} \left( \mathbf{FT}_{\text{Align}} \left( \mathcal{A}^{\mathbb{Z}^2} \right), \mathbf{T}_{\text{Clock}}, \mathcal{A}_{\mathcal{M}_{\text{Forbid}}}^{\mathbb{Z}^2}, \mathcal{A}_{\mathcal{M}_{\text{Search}}}^{\mathbb{Z}^2} \right)$$

To obtain  $\Sigma$  :

- operation **Fact** to keep only letters of  $\mathcal{A}_{\Sigma}$
- operation **SA** to keep only an horizontal line

# Application 1: An order on subshifts

A *Turing machine with semi-oracle*  $\mathcal{L}$  has the following behaviour: the machine reads an entry pattern  $p$  and writes a pattern on the oracle tape, until the state  $q_?$  is reached. If the pattern written on the oracle tape is in  $\mathcal{L}$  then the machine stops, else it keeps on calculating.

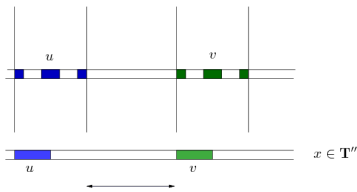
We can define the following semi-order:

$$\mathcal{L} \preceq \mathcal{L}' \iff \exists \mathcal{M}^{\mathcal{L}'} \text{ a Turing machine with semi-oracle } \mathcal{L}' \\ \text{such that } \text{dom}(\mathcal{M}^{\mathcal{L}'}) = \mathcal{L}.$$

## Theorem

Let  $\mathbf{T}$  be a strongly specified subshift, one has:

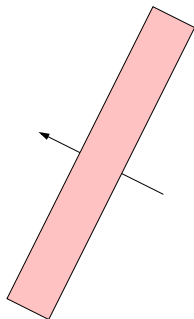
$$Cl_{\text{Prod,Fact,FT,SA,SE}}(\mathbf{T}) = \{\mathbf{T}_{\mathcal{L}} : \mathcal{L} \preceq \mathcal{L}(\mathbf{T})^c\}.$$





## Application 2: Expansive directions

Let  $\Sigma \subset \mathcal{A}^{\mathbb{Z}^2}$  be a subshift.  $\Sigma$  is *expansive* according a line  $\Delta$  if two configurations  $x, y \in \Sigma$  are similar around  $\Delta$ , then  $x = y$ .



### Theorem

For an effective subshift, the bounds of expansive cone are exactly given by effective number.

What happen for sofic subshift?

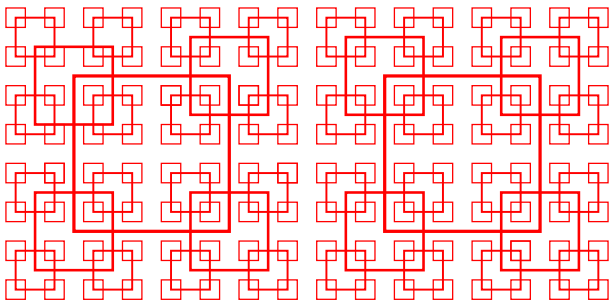
## Application 3: Effective multidimensional S-adic systems

Let  $s_1 : \square * \rightarrow \begin{array}{|c|c|} \hline * & * \\ \hline * & * \\ \hline \end{array}$  and  $s_2 : \square * \rightarrow \begin{array}{|c|c|} \hline * & * \\ \hline * & * \\ \hline \end{array}$  be two square substitutions.

Let  $(\tau_i)_{\mathbb{N}}$  be an effective sequence of  $\{0; 1\}$ .

Define the effective multidimensional  $\{s_1; s_2\}$ -adic systems following  $\tau$ :

$$\mathbf{T} = \{x \in \mathcal{A}^{\mathbb{Z}^2} : \text{admissible patterns are } s_{\tau_0} \circ s_{\tau_1} \circ \cdots \circ s_{\tau_{k-1}} \circ s_{\tau_k}(\square)\}$$



### Theorem

Effective multidimensional S-adic systems are sofic.

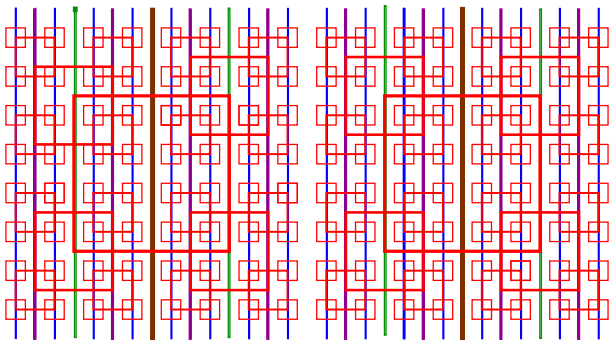
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## Application 4: Discrete plane