Parameterized Verification of Synchronization in constrained reconfigurable broadcast networks

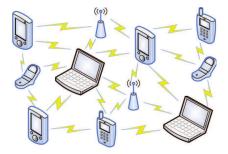
Nathalie Bertrand

Inria & IRISA

joint work with Balasubramanian A.R. (CMI) and Nicolas Markey (CNRS & IRISA)

TACAS @ ETAPS 2018

Formal Models for Ad Hoc Networks



Formal Models for Ad Hoc Networks



important features

- mobile nodes
- unknown initial topology
- communication by broadcasts to neighbours

Formal Models for Ad Hoc Networks



important features

- mobile nodes
- unknown initial topology
- communication by broadcasts to neighbours

broadcast networks with evolving communication topology

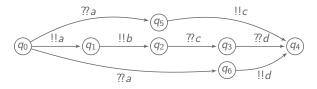
Constrained reconfiguration in Broadcast Networks - Nathalie Bertrand

Reconfigurable Broadcast Networks

- nodes execute each a finite-state process
- finitely many types of processes
- broadcasts to neighbours
- evolving communication topology

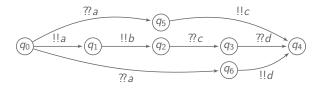
Reconfigurable Broadcast Networks

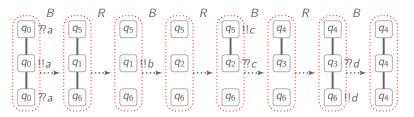
- nodes execute each a finite-state process
- finitely many types of processes
- broadcasts to neighbours
- evolving communication topology



Reconfigurable Broadcast Networks

- nodes execute each a finite-state process
- finitely many types of processes
- broadcasts to neighbours
- evolving communication topology





Constrained reconfiguration in Broadcast Networks - Nathalie Bertrand

parameter: initial configuration (number of nodes and topology)

Parameterized verification: check that a property holds for all parameter values, and all executions.

parameter: initial configuration (number of nodes and topology)

Parameterized verification: check that a property holds for all parameter values, and all executions.

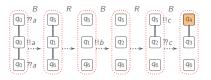
Dually, looking for counterexamples: $\exists \gamma_0 \rightarrow \gamma_1 \rightarrow \cdots \models \varphi$?

parameter: initial configuration (number of nodes and topology)

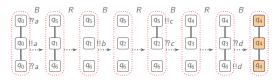
Parameterized verification: check that a property holds for all parameter values, and all executions.

Dually, looking for counterexamples: $\exists \gamma_0 \rightarrow \gamma_1 \rightarrow \cdots \models \varphi$?

Reachability



Synchronization



Constrained reconfiguration in Broadcast Networks - Nathalie Bertrand

Theorem[Delzanno et al. Concur'10]Parameterized reachability and synchronization are decidable in PTIME.

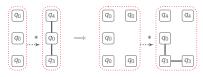
Theorem

[Delzanno et al. Concur'10]

Parameterized reachability and synchronization are decidable in PTIME.

- reachability: saturation algorithm, starting with $\{q_0\}$
- synchronization: forward and backward iterative pruning of broadcast protocol, using algorithm for reachability

Monotonicity property: if a configuration is reachable, then all configurations obtained by duplicating some nodes are also reachable



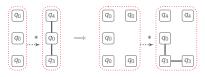
Theorem

[Delzanno et al. Concur'10]

Parameterized reachability and synchronization are decidable in PTIME.

- reachability: saturation algorithm, starting with $\{q_0\}$
- synchronization: forward and backward iterative pruning of broadcast protocol, using algorithm for reachability

Monotonicity property: if a configuration is reachable, then all configurations obtained by duplicating some nodes are also reachable



Rk: both problems are undecidable under fixed topology

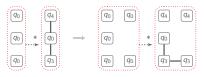
Theorem

[Delzanno et al. Concur'10]

Parameterized reachability and synchronization are decidable in PTIME.

- reachability: saturation algorithm, starting with $\{q_0\}$
- synchronization: forward and backward iterative pruning of broadcast protocol, using algorithm for reachability

Monotonicity property: if a configuration is reachable, then all configurations obtained by duplicating some nodes are also reachable

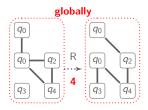


Rk: both problems are undecidable under fixed topology Limitation: arbitrary reconfigurations between communications

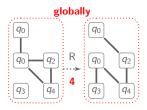
this talk: towards realistic representation of mobility

Constrained reconfiguration in Broadcast Networks - Nathalie Bertrand

Quantifying reconfiguration: number of modified links



Quantifying reconfiguration: number of modified links

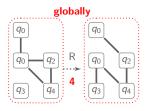


k-bounded execution





Quantifying reconfiguration: number of modified links



k-bounded execution



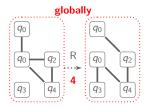


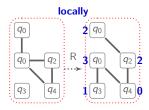
k-bounded-on-average execution





Quantifying reconfiguration: number of modified links





k-bounded execution



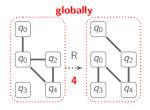


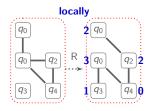
k-bounded-on-average execution





Quantifying reconfiguration: number of modified links





k-bounded execution





k-bounded-on-average execution







locally-k-bounded execution



TACAS, 18 April 2018- 6/ 13

Reachability under reconfiguration constraints

There exists a reaching execution iff there exists a *-bounded reaching execution.

Proof idea: interleave several copies of a witness execution only the first copy needs to reach the target

Reachability under reconfiguration constraints

There exists a reaching execution iff there exists a *-bounded reaching execution.

Proof idea: interleave several copies of a witness execution only the first copy needs to reach the target

Rest of the talk: synchronization

There exists a *k*-bounded synchronizing execution iff there exists a *k*-bounded-on-average synchronizing execution.

There exists a *k*-bounded synchronizing execution iff there exists a *k*-bounded-on-average synchronizing execution.

Proof idea for right-to-left implication with k = 1Potential function along execution

- initially 0
- increases by k (here 1) in broadcast steps
- decreases by number of modified links in reconfigurations steps

There exists a *k*-bounded synchronizing execution iff there exists a *k*-bounded-on-average synchronizing execution.

Proof idea for right-to-left implication with k = 1Potential function along execution

- initially 0
- increases by k (here 1) in broadcast steps
- decreases by number of modified links in reconfigurations steps

Decomposition of execution w.r.t sign of potential

potential



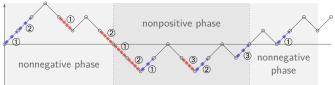
There exists a *k*-bounded synchronizing execution iff there exists a *k*-bounded-on-average synchronizing execution.

Proof idea for right-to-left implication with k = 1Potential function along execution

- initially 0
- increases by k (here 1) in broadcast steps
- decreases by number of modified links in reconfigurations steps

Decomposition of execution w.r.t sign of potential

potential



Correspondence between repeated broadcasts, and repeated link modifications

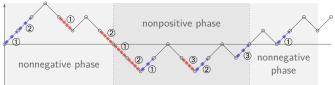
There exists a *k*-bounded synchronizing execution iff there exists a *k*-bounded-on-average synchronizing execution.

Proof idea for right-to-left implication with k = 1Potential function along execution

- initially 0
- increases by k (here 1) in broadcast steps
- decreases by number of modified links in reconfigurations steps

Decomposition of execution w.r.t sign of potential

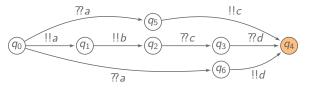
potential



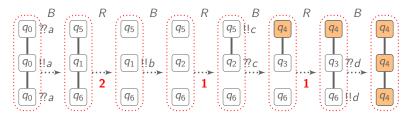
Correspondence between repeated broadcasts, and repeated link modifications Interleave duplicates of initial execution to strictly alternate +1 and -1 steps

There may exist a synchronizing execution, while no 1-bounded synchronizing execution exists.

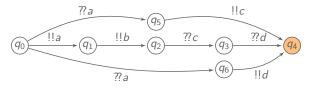
There may exist a synchronizing execution, while no 1-bounded synchronizing execution exists.



unspecified receptions lead to a sink



There may exist a synchronizing execution, while no 1-bounded synchronizing execution exists.

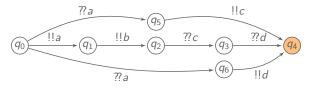


unspecified receptions lead to a sink

 \ddagger nodes: x for top branch; y for central branch; z: for bottom branch In any synchronizing execution

- \ddagger broadcast steps = x + 2y + z
- \ddagger reconfigured links $\ge x + 2y + z$

There may exist a synchronizing execution, while no 1-bounded synchronizing execution exists.



unspecified receptions lead to a sink

 \ddagger nodes: x for top branch; y for central branch; z: for bottom branch In any synchronizing execution

- \ddagger broadcast steps = x + 2y + z
- \ddagger reconfigured links $\ge x + 2y + z$

In 1-bounded executions: \sharp broadcast steps $\geq 1 + \sharp$ reconfigured links

There exists a synchronizing execution iff there exists a 1-locally-bounded synchronizing execution.

There exists a synchronizing execution iff there exists a 1-locally-bounded synchronizing execution.

For $f : \mathbb{N} \to \mathbb{N}$ is a diverging function f(n)-bounded: reconfigurations in executions over configurations of size n concern at most f(n) link

There exists a synchronizing execution iff there exists a f(n)-bounded synchronizing execution.

There exists a synchronizing execution iff there exists a 1-locally-bounded synchronizing execution.

For $f : \mathbb{N} \to \mathbb{N}$ is a diverging function f(n)-bounded: reconfigurations in executions over configurations of size n concern at most f(n) link

There exists a synchronizing execution iff there exists a f(n)-bounded synchronizing execution.

Corollary

The parameterized synchronization problem is in PTIME when restricting to either 1-locally-bounded, or f(n)-bounded executions.

The parameterized synchronization problem is undecidable when restricting to *k*-**bounded executions**.

It is decidable for *k*-bounded executions with rendez-vous.

The parameterized synchronization problem is undecidable when restricting to *k*-**bounded executions**.

It is decidable for *k*-bounded executions with rendez-vous.

Proof idea: encoding into Petri net reachability

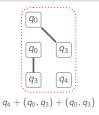
rendez-vous communications ⇒ at most one neighbour per node finitely many patterns

The parameterized synchronization problem is undecidable when restricting to *k*-**bounded executions**.

It is decidable for *k*-bounded executions with rendez-vous.

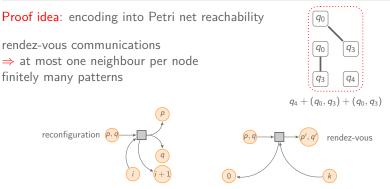
Proof idea: encoding into Petri net reachability

rendez-vous communications ⇒ at most one neighbour per node finitely many patterns



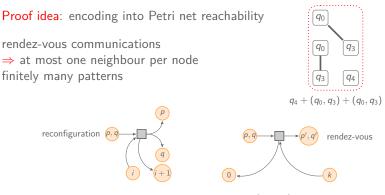
The parameterized synchronization problem is undecidable when restricting to k-**bounded executions**.

It is decidable for *k*-bounded executions with rendez-vous.



The parameterized synchronization problem is undecidable when restricting to *k*-**bounded executions**.

It is decidable for *k*-bounded executions with rendez-vous.



initialisation generate tokens in places q_0 and (q_0, q_0) simulation reconfigurations and rendez-vous communications termination emptying tokens from target place

Constrained reconfiguration in Broadcast Networks - Nathalie Bertrand

Summary of results

Constraining reconfigurations in broadcast protocols

Contributions

- equivalence of k-bounded and k-bounded-on-average
- ▶ non-equivalence of 1-bounded with unconstrained reconfiguration
- undecidability of synchronization under k-bounded assumption
- decidability assuming rendez-vous communications

Techniques

- duplication of executions and clever interleaving
- encoding of 2-counter machine
- reduction to reachability in Petri net

Future work

Quantitative impact of reconfiguration restrictions

- minimum number of nodes in a witness execution
- mininum number of steps to synchronize

Long-term objective: realistic model of mobility in ad hoc networks

- representing with physical constraints: speed of nodes vs communication rate
- exploiting statistical analysis of real behaviours