

A Control-Theory Standpoint for the Non-emptiness Problem of Automata

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Control Problems

Partial Observation

Application to Non-deterministic Word Automata

Application to Alternating Word Automata

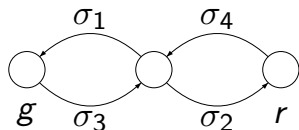
A word on Tree Automata

Possible Directions

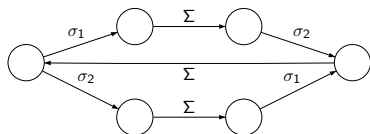
Control Problems

- ▶ \mathcal{S} a Labeled Transition Systems
- ▶ The Control Objective is given, e.g. by a formula ϕ
- ▶ The problem to solve is:
Find an LTS \mathcal{C} such that the executions of $\mathcal{C} \times \mathcal{S}$ satisfy ϕ

Control Objective = $\forall(\mathbf{F}^{\infty} g \Rightarrow \mathbf{F}^{\infty} r)$

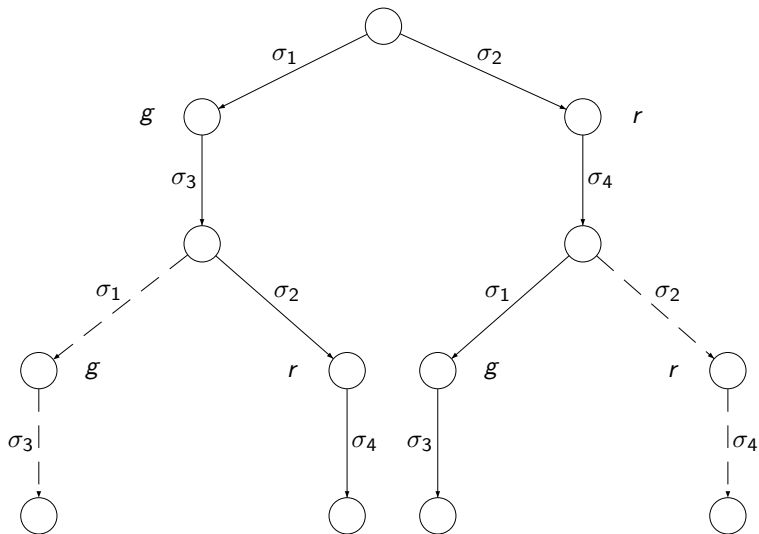


A possible controller \mathcal{C}



By the product with \mathcal{C} , the system behaviour is pruned.

The computation tree of $\mathcal{C} \times \mathcal{S}$ looks like (solid lines):



and indeed $\mathcal{C} \times \mathcal{S} \models \forall (\mathbf{F} g \Rightarrow \mathbf{F} r)$

- ▶ Additionally, we may require properties on \mathcal{C} :

Controllability: $\Sigma = \Sigma_c \uplus \Sigma_{uc}$
AG ($\bigwedge_{\sigma \in \Sigma_{uc}} \langle \sigma \rangle \text{true}$)

Non-blocking: **AG** ($\bigvee_{\sigma \in \Sigma} \langle \sigma \rangle \text{true}$)

Observability: $\Sigma_o \subseteq \Sigma$ (a projection)

Indistinguishability: $M : \Sigma \rightarrow \Delta \cup \{\tau\}$

Controllers as Strategies

- ▶ $\mathcal{G} = (V, E)$ an arena (turned-based two-player) $V = V_0 \uplus V_1$
- ▶ Alphabet of moves: $\Sigma_0 \uplus \Sigma_1$
- ▶ A winning condition (e.g. Buchi, a proposition acc)
- ▶ Find a controller \mathcal{C} such that

$$\left\{ \begin{array}{l} \mathcal{C} \times \mathcal{G} \models \forall \mathbf{F}^{\infty} acc \\ \mathcal{C} \models \mathbf{AG} (\bigwedge_{\sigma \in \Sigma_1} \langle \sigma \rangle \text{true}) \end{array} \right.$$

Controller Synthesis for Deterministic Systems

[AVW03]

- ▶ A quotient construction

$$\mathcal{C} \times \mathcal{S} \models \Phi \text{ iff } \mathcal{C} \models \Phi/\mathcal{S}$$

Based on automata: $\Phi \rightsquigarrow \mathcal{A}_\Phi$. Then $\mathcal{A}_\Phi/\mathcal{S}$ is a product between \mathcal{A}_Φ and \mathcal{S} which updates the properties required in \mathcal{A}_Φ according to those of \mathcal{S} .

- ▶ Synthesis: Find a model of

$$\Phi/\mathcal{S} \wedge \Psi$$

Control Problems under Partial Observation

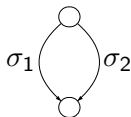
- ▶ [AVW03,Briand06] Impose the structure of the controller

(non-)Observability



if $\sigma \notin \Sigma_o$

Indistinguishability



if $M(\sigma_1) = M(\sigma_2)$

- ▶ Strict extension of tree automata,
not bisimulation invariant, BUT still decidable!

Partial Observation Specifications

- ▶ Observability ($\Sigma_o \subseteq \Sigma$)

- ▶ [AVW03]

$$\mathbf{AG} \left(\bigwedge_{\sigma \notin \Sigma_o} \circlearrowleft^{\sigma} \right)$$

- ▶ [PR05] use no loop but another product:

$$(\mathcal{C} \text{ is over } \Sigma_o \text{ and } \mathcal{C} \otimes \mathcal{S} \models \Phi) \text{ iff } \mathcal{C} \models \Phi // \mathcal{S}$$

Can express maximal permissiveness

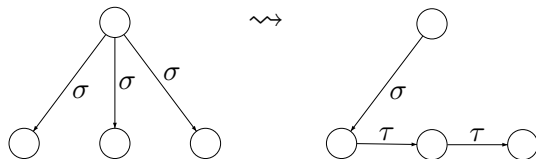
- ▶ Indistinguishability ($M : \Sigma \rightarrow \Delta \cup \{\tau\}$)

- ▶ [Briand06]

$$\mathbf{AG} \left(\bigwedge_{M(\sigma_1)=M(\sigma_2)} \sigma_1 \Downarrow \sigma_2 \wedge \bigwedge_{M(\sigma)=\tau} \circlearrowleft^{\sigma} \right)$$

Controller Synthesis for Non-deterministic Systems

\mathcal{S} over $\Sigma \rightsquigarrow \tilde{\mathcal{S}}$ over $\Sigma \cup \{\tau\}$



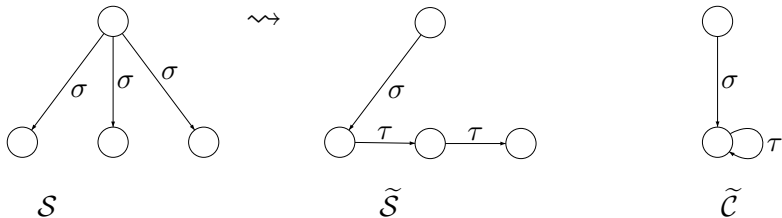
Lemma[RP05] If \mathcal{S} is finite, so is $\tilde{\mathcal{S}}$ (polynomial).

Transform Φ into $\tilde{\Phi}$ according to $\widetilde{\langle \sigma \rangle \Phi'} = \langle \sigma \tau^* \rangle (\tilde{\Phi}')$

Theorem [RP05]

$$\mathcal{C} \times \mathcal{S} \models \Phi \Leftrightarrow \tilde{\mathcal{C}} \times \tilde{\mathcal{S}} \models \tilde{\Phi}, \text{ and}$$
$$\tilde{\mathcal{C}} \models \mathbf{AG}(\langle \sigma \rangle \wedge \langle \tau \rangle \text{true})$$

(\mathcal{C} does not observe τ nor control it)



\mathcal{C} is obtained by removing the τ -loops in $\tilde{\mathcal{C}}$

Non-deterministic Word Automata

- ▶ $\mathcal{B} = (A, Q, q_0, \delta, Acc)$ where $\delta \subseteq Q \times \Sigma \times Q$

$$\delta(q, a) = q_1 \vee \dots \vee q_n$$

- ▶ w is accepted by \mathcal{B} if there exists a run $q_0q_1q_2 \dots \in Acc$ with $q_i \in \delta(q_{i-1}, w(i)), \forall i \leq 1$.
- ▶ Consider the following (decidable) problems:
 - ▶ Emptiness: “is there a word accepted by \mathcal{B} ?”
 - ▶ Universality: “is there a word rejected by \mathcal{B} ?”

Emptiness and Universality

- ▶ $\mathcal{B} = (A, Q, q_0, \delta, Acc)$ becomes a non-deterministic system
- ▶ $\mathcal{S}_{\mathcal{B}} = (Q, \delta, q_0, \rightarrow)$ over $\Sigma = A$, and define ϕ_{Acc}
- ▶ The controller chooses the letter(s) a , hence $\Sigma_{\mathcal{C}} = A$
- ▶ The system chooses the run (a path)

The product $\mathcal{C} \times \mathcal{S}_{\mathcal{B}}$ is the tree of all runs on the word chosen by \mathcal{C} .

Emptiness and Universality

Theorem

(Emptiness) $L(\mathcal{B}) \neq \emptyset$ iff there exists $\tilde{\mathcal{C}}$ such that

$$\left\{ \begin{array}{l} \tilde{\mathcal{C}} \times \tilde{\mathcal{S}}_{\mathcal{B}} \models \exists \phi_{Acc} \\ \tilde{\mathcal{C}} \models \mathbf{AG} (\circlearrowleft^{\tau} \wedge \langle \tau \rangle true) \\ (\tilde{\mathcal{C}} \text{ is non-blocking} \dots) \end{array} \right.$$

Theorem

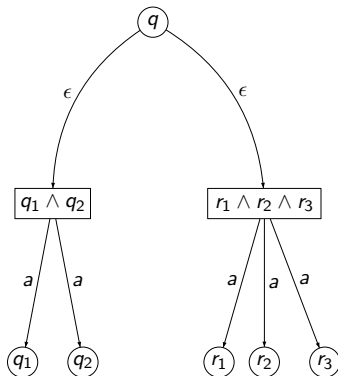
(Universality) $L(\mathcal{B}) \neq A^{\omega}$ iff there exists $\tilde{\mathcal{C}}$ such that

$$\left\{ \begin{array}{l} \tilde{\mathcal{C}} \times \tilde{\mathcal{S}}_{\mathcal{B}} \models \forall \neg \phi_{Acc} \\ \tilde{\mathcal{C}} \models \mathbf{AG} (\circlearrowleft^{\tau} \wedge \langle \tau \rangle true) \\ (\tilde{\mathcal{C}} \text{ is non-blocking} \dots) \end{array} \right.$$

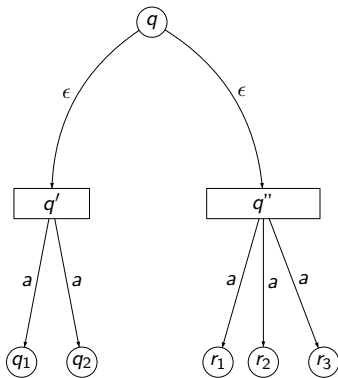
Alternating Word Automata

$\mathcal{A} = (A, Q, q_0, \delta, Acc)$ where $\delta : Q \times \Sigma \rightarrow B^+(Q)$

$$\delta(q, a) = (q_1 \wedge q_2) \vee (r_1 \wedge r_2 \wedge r_3)$$



Write T for the set of transitions of the automaton $(q, \epsilon, q'), (q', a, q_1), \dots$



Alternation \rightsquigarrow Partial Observation

- ▶ \mathcal{A} becomes a mere system $\mathcal{S}_{\mathcal{A}}$ over T (the transitions of \mathcal{A})
- ▶ Alternation is captured by a game between the controller and the system; the controller only knows the word built so far.

- ▶ The controller chooses the letter(s) a , and the disjunct in $\delta(q, a)$:

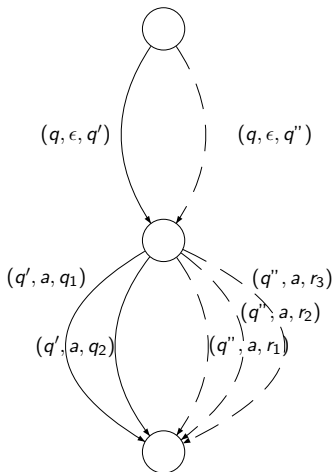
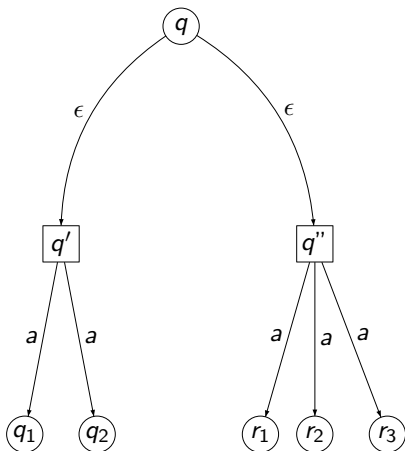
$$\Sigma_c = \{(q, \epsilon, q') \mid (q, \epsilon, q') \in T\}$$

and

$M((q_1, \epsilon, q')) = M((q_2, \epsilon, q''))$, as no additional information is given

- ▶ The system chooses the a -successor state:

$$M((q', a, \dots)) = M((q'', a, \dots))$$



The product $\mathcal{C} \times \mathcal{S}_{\mathcal{A}}$ is a run (a tree) of \mathcal{A} on the word chosen by \mathcal{C} .

Emptiness and Universality

Let $\mathcal{A} = (A, Q, q_0, \delta, Acc)$, and define ϕ_{Acc}

Theorem

(Emptiness) $L(\mathcal{A}) \neq \emptyset$ iff there exists \mathcal{C} such that

$$\left\{ \begin{array}{l} \mathcal{C} \times \mathcal{S}_{\mathcal{A}} \models \forall \phi_{Acc} \\ \mathcal{C} \models \mathbf{AG} (\bigwedge_{a \in A} \langle (q, a, q') \rangle true \wedge \bigwedge (q_1, \epsilon, q') \Downarrow (q_2, \epsilon, q'') \wedge \bigwedge (q', a, q) \Downarrow (q'', a, r)) \\ \dots \end{array} \right.$$

Theorem

(Universality) $L(\mathcal{A}) \neq A^\omega$ iff there exists \mathcal{C}' such that

$$\left\{ \begin{array}{l} \mathcal{C}' \times \mathcal{S}_{\mathcal{A}} \models \forall \neg \phi_{Acc} \\ \mathcal{C}' \models \mathbf{AG} (\bigwedge \langle (q, \epsilon, q') \rangle true \wedge \bigwedge (q_1, \epsilon, q') \Downarrow (q_2, \epsilon, q'') \wedge \bigwedge (q', a, q) \Downarrow (q'', a, r)) \\ \mathcal{C}' \models \mathbf{AG} (\bigwedge_{q', a} \bigvee \langle (q', a, q) \rangle true) \dots \end{array} \right.$$

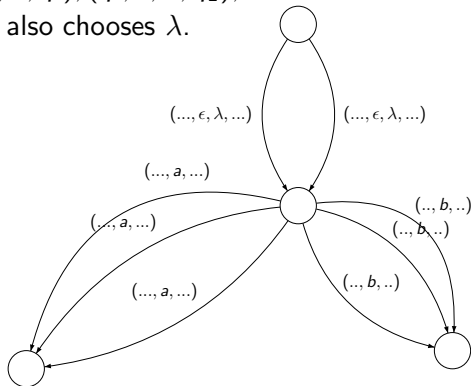
The product $\mathcal{C}' \times \mathcal{S}_{\mathcal{A}}$ is a tree which contains a branch of every possible run of \mathcal{A} on the word chosen by \mathcal{C}' .

Tree Automata

- ▶ Have to take propositions into account:

$$\delta(q, \lambda) = [(a, q_1) \wedge (a, q_2) \wedge (b, q_3)] \vee [(a, q'_1) \wedge (b, q'_2) \wedge (b, q'_3)]$$

- ▶ Alphabet $(q, \epsilon, \lambda, q')$, $(q', a, \lambda, q_1), \dots$
- ▶ The controller also chooses λ .



Possible Directions



- ▶ Two-way Automata

- ▶ [Briand06] with \circlearrowleft^η , where $\eta \in \Sigma^*$.
- ▶ Undecidable for $|\eta| \geq 3$ (grids: \circlearrowleft^{abc} , \circlearrowleft^{bac} , \circlearrowleft^{cd})
- ▶ BUT open problem for $|\eta| \leq 2$.

- ▶ Automata with Constraints

- ▶ Automata with Equality and Disequality Constraints [TATA book] Undecidable
- ▶ Decidable subclasses, e.g. Automata With Constraints Between Brothers

Conclusion

- ▶ A novel standpoint to improve our insights
In particular, regarding **Alternation**
- ▶ Extend this standpoint to other classes of automata.
- ▶ Exploit controllers properties in this setting (maximal permissiveness, fairness, etc.).