

$x_1$

$x_2$

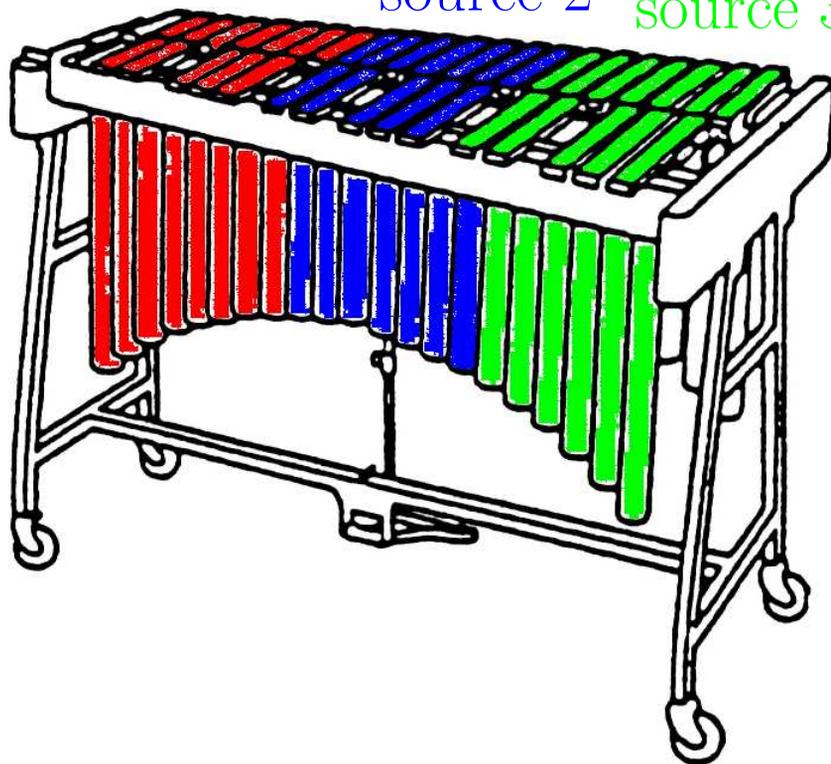


Capteurs

source 1

source 2

source 3



Sources diffuses  
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