

Summary of last class

- **Problem**: represent the time-varying frequency content of time series
- **Tool**: Short Time Fourier Transform (STFT)
 - definition
 - role of the analysis window (size & shape)
 - perfect reconstruction with synthesis window
- **Applications**: time-frequency processing
 - Effect of redundancy of STFT

Today's program

- **Solutions** of Exercise
- From signals (ID) to images (2D)
- **Tool**: multiresolution analysis (ID & 2D)
 - 2D Fourier transform
 - pyramidal representations & wavelets
- Applications: Denoising & Inpainting
- Concept of sparsity



Example : Hann window

- Analysis window, synthesis window $w[n] = \frac{1}{2} \left(1 - \cos 2\pi \frac{n}{N} \right), \ 0 \le n < N$ w'[n] = 1
- Half-overlapping window, hop size = T = N/2
- **Exercice I**: check the reconstruction condition
 - Hint: $(1 \cos t)/2 = \sin^2 t/2$
- **Exercice 2**: idem with sine window

$$w[n] = w'[n] = \sin \pi \frac{n}{N}, \ 0 \le n < N$$

Solution

- What we need to check $f[n] := \sum_{r=-\infty}^{+\infty} w[n-rT]w'[n-rT] = 1, \forall n \in \mathbb{Z}$
- f[n] is T-periodic: so only need to check $f[n] = 1, 0 \le n < T = N/2$



From signals to images

2D Fourier transform

• Definition
$$X(\vec{f}) := \int \int x(\vec{p}) e^{-2i\pi f_1 p_1 - 2i\pi f_2 p_2} dp_1 dp_2$$

- Same properties as ID Fourier transform
- Rotation $R_{ heta} := \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}$ $X(R_{-\theta}\vec{p}) \qquad X(R_{-\theta}\vec{f})$
- Separable images / tensor products $x_1(p_1)\cdot x_2(p_2) \qquad X_1(f_1)\cdot X_2(f_2)$



Example

• A natural image and its Fourier transform



- Low frequency content is dominant
- Some horizontal & vertical edges
- Spatial information is hard to extract

Multiresolution representations

Multiscale image representations

- Low frequency content = low-resolution image approximation = coarse image
- High-frequency content = details
- Idea = coarse to fine description of images
 - pyramidal representation [Burt & Adelson]
 - wavelets [Mallat, Daubechies, Meyer, Vetterli, ...]





ID subsampled filterbanks

 Subsampling at each low-pass / high-pass to remove unnecessary redundancy







Time-frequency tiling $2^{j/2}\psi(2^jt-k)$

- Dilation + translation of mother wavelet $\psi(t)$
- Time-frequency localization of wavelets



ID orthonormal wavelets

- Detail coefficients at scale j $d_{j,k} = \langle x, \psi_{j,k} \rangle$ $\psi_{j,k}(t) = 2^{j/2} \psi(2^j t - k)$ mother wavelet function $- \sqrt{1}$
- Coarse coefficients at scale j $S_{j,k} = \langle x, \phi_{j,k} \rangle$ $\phi_{j,k}(t) = 2^{j/2} \phi(2^j t - k)$ scaling function
- Reconstruction $x = \sum_{j=0}^{J} \sum_{k} \langle x, \psi_{j,k} \rangle \psi_{j,k} + \sum_{k} \langle x, \phi_{J,k} \rangle \phi_{J,k}$
- Orthonormal Basis $\{\psi_{j,k}\}_{j,k}\cup\{\phi_{J,k}\}_k$

Choice of the mother wavelet

- Through the choice of H and G QMF filters
- Main characteristics to consider
 - vanishing moments = level of oscillations

 $\int \psi(t)t^n dt = 0, 0 \le n \le N \quad \text{and} \quad \langle x, \psi_{j,k} \rangle \approx 0$ on smooth parts of signal/.image

• length [shorter = faster convolution]

• regularity



2D orthonormal wavelets

 ID filters applied alternatively on rows/ columns of the image, considered as ID signals



Η

LL

LH

HL

HH

R. Gribonval, cours "Traitements et Transformations", module "Acquisition et Représentations de Données" Parcours "Image et Données", Master 2 Recherche en Informatique, Université de Rennes I



Example of 2D wavelet transform

• 3 layers of decomposition





2D separable orthonormal wavelets

- ID wavelets $\{\psi_{j,k}\}_{j,k} \cup \{\phi_{J,k}\}_k$
- 2D wavelet coefficients
 - LL $\langle x, \phi_{j,k}(p_1)\phi_{j,k}(p_2)\rangle$
 - **HL** $\langle x, \psi_{j,k}(p_1)\phi_{j,k}(p_2)\rangle$
 - LH $\langle x, \phi_{j,k}(p_1)\psi_{j,k}(p_2)\rangle$
 - HH $\langle x, \psi_{j,k}(p_1)\psi_{j,k}(p_2)\rangle$



Wavelet domain processing

Wavelet Domain Denoising

Courtesy: G. Peyré, Ceremade, Université Paris 9 Dauphine



Image inpainting

Courtesy: G. Peyré, Ceremade, Université Paris 9 Dauphine



Parcours "Image et Données", Master 2 Recherche en Informatique, Université de Rennes I



Inpainting problem

- Given: partial observation $y = \mathbf{M} x = \mathbf{M} \mathbf{\Phi} c$
- **Goal**: recover image x / representation c
- **Issue**: less equations than unknowns
- **Approach**: exploit sparsity of c





Sparse Overcomplete Representations



Sparse representations

• Fourier / DCT / wavelet orthonormal basis

$$x = \sum_{k} \langle x, g_k \rangle g_k \in \mathbb{R}^N$$

- Notion of sparsity
 - few significant coefficients
 - good approximation with few elements
- Related to good compression properties
- Need to adapt basis to type of signals to approximate / compress

Compression & approximation



Which representation for which signals ?

- Harmonic signals : Fourier basis
- Locally harmonic signals : MDCT (STFT)
- Piecewise smooth signals : wavelets
- Superposition of different "layers" ?
 - Audio = transients + harmonics !
 - Images = contours + textures !



Adaptive representation with dictionaries

- Time-frequency representation $x(\tau) = \sum_{t,f} X(t,f) w_{t,f}(\tau)$ Time-scale representations $x(\tau) = \sum \langle x, \psi_{j,k} \rangle \psi_{t,s}(\tau)$

j,k

- General model :
 - redundant dictionary of atoms $g_k(t)$
 - linear synthesis $x(t) \approx \sum a_k g_k(t)$
- Objective : compute representation $\{a_k^k\}$

Redundant dictionaries

- There are more basis vectors than the signal dimension $\{g_k[n]\}_{k=1}^K$ $x = (x[n])_{n=1}^N, N < K$
- There are infinitely many possible representations

• Preferably choose sparse representations

Greedy algorithms

- Idea : the most significant components are associated to large inner products
- Matching Pursuit = iterative greedy algorithm
 - pick the best atom

$$k_i := \arg\max_k |\langle x^{(i)}, g_k \rangle|$$

- remove it from the residual $x^{(i+1)} := x^{(i)} \langle x^{(i)}, g_{k_i} \rangle g_{k_i}$ after M steps $x = \sum_{i=0} \langle x^{(i)}, g_{k_i} \rangle g_{k_i} + x^{(M)}$
- Orthogonal Matching Pursuit : $x^{(i+1)} := x^{(i)} \sum_{l=0}^{i-1} \alpha_l^{(i)} g_{k_i}$

(Mean Square Error projection)

Summary: key concepts

- Convolution: definition, main properties
- Fourier transform: definition, main properties
- Fast convolution: overlap-add algorithm
- Short-time Fourier transform: definition, role of the window, reconstruction
- Wavelet transform: principle, ID & 2D
- Notion of sparsity: role in data compression