Co-simulation of AADL and Simulink models using **Polychrony on Polarsys**

An Eclipse project of the Polarsys **Industry Working Group**

https://polarsys.org/projects/polarsys.pop



INRIA project-team TEA

Time

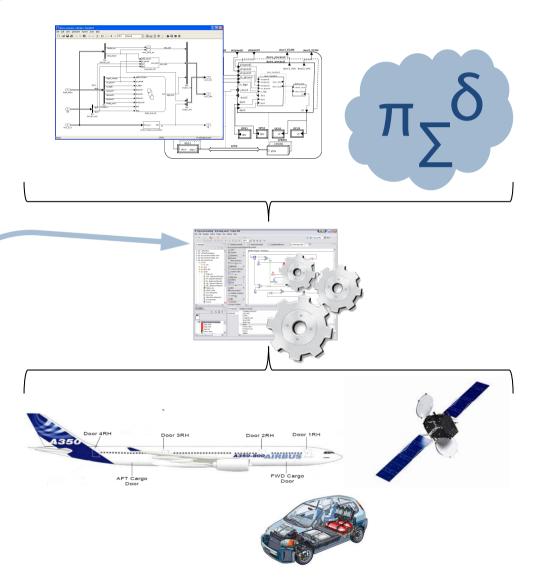
Events

Architectures

Formal methods for embedded system design

Focus on time modelling from an architecture perspective

Eclipse project POP for the opensource distribution of the toolset Polychrony on the platform of the Polarsys Industrial Working Group



Polychrony on Polarsys (POP)

An Eclipse project integrated in the platform of the Polarsys Industry Working Group

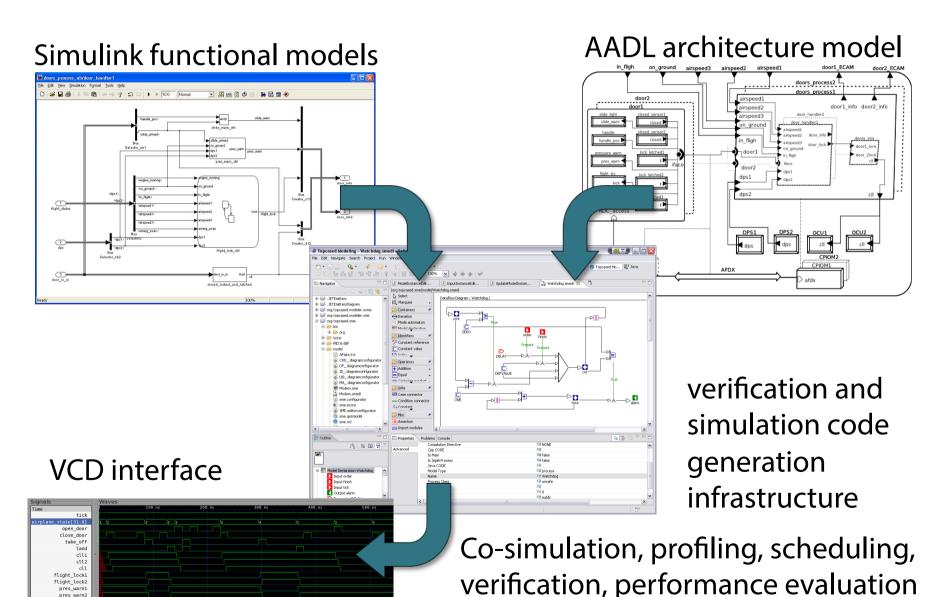
An implementation of the synchronous multi clocked model of computation of the data-flow language Signal



A toolbox for synthesis in computer-aided system design consisting of transformations, verification, and code generation functionalities



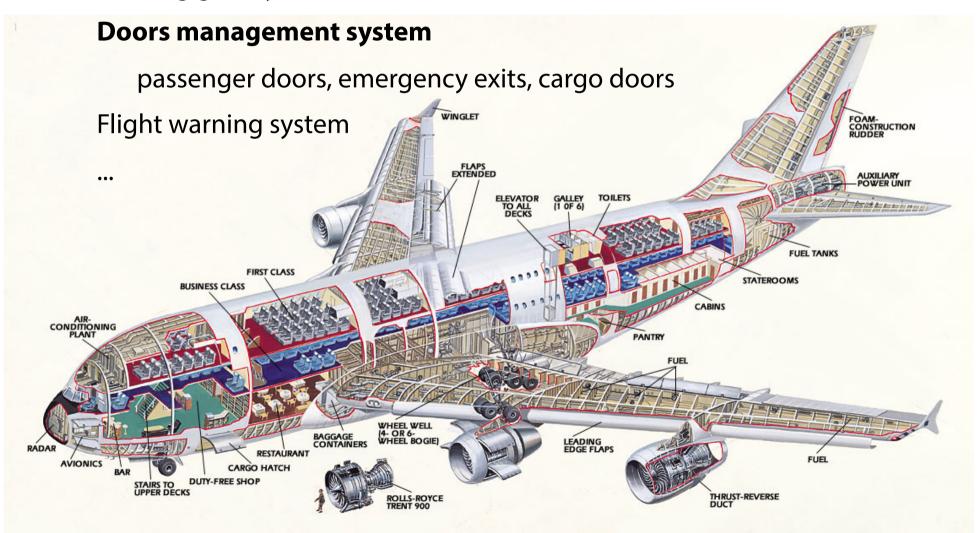
Case study of the A350 doors management system



Case study of the A350 doors management system

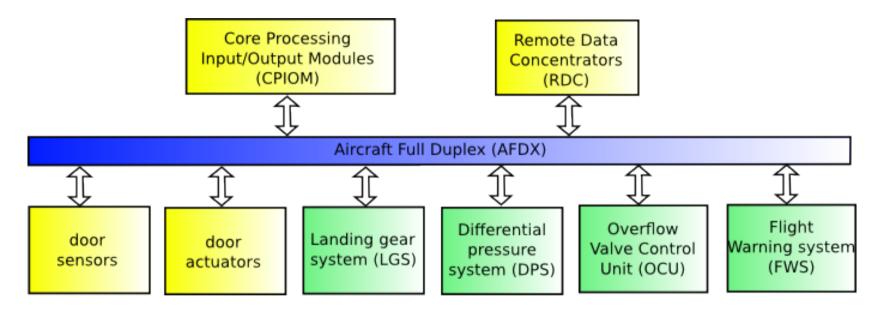
Flight control systems

Landing gear system



Case study of the A350 doors management system

System-level model of the Doors and Slides Control System (SDSCS)



Function

Monitor doors status via sensors

Control flight lock actuators

Manage the residual pressure

Inhibit incorrect cabin pressure

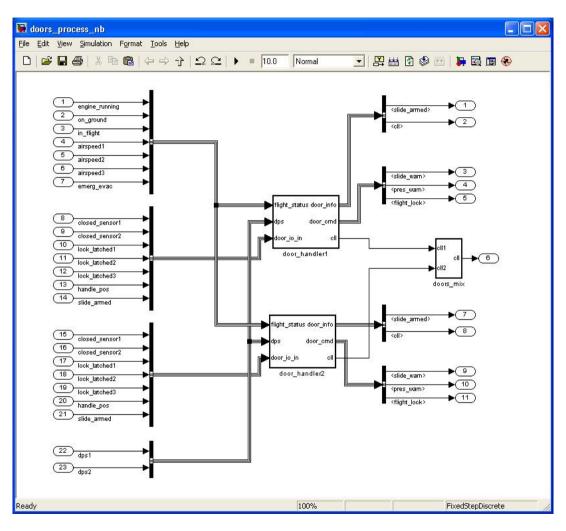
A safety-critical system

High-level modeling

Early validation & verification

Architecture exploration

SDSCS functional model (Simulink)



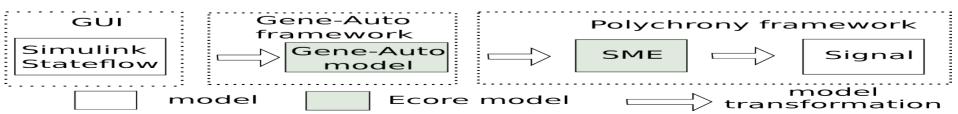
Simulink

Matlab Simulink and Stateflow, a popular high-level modeling language

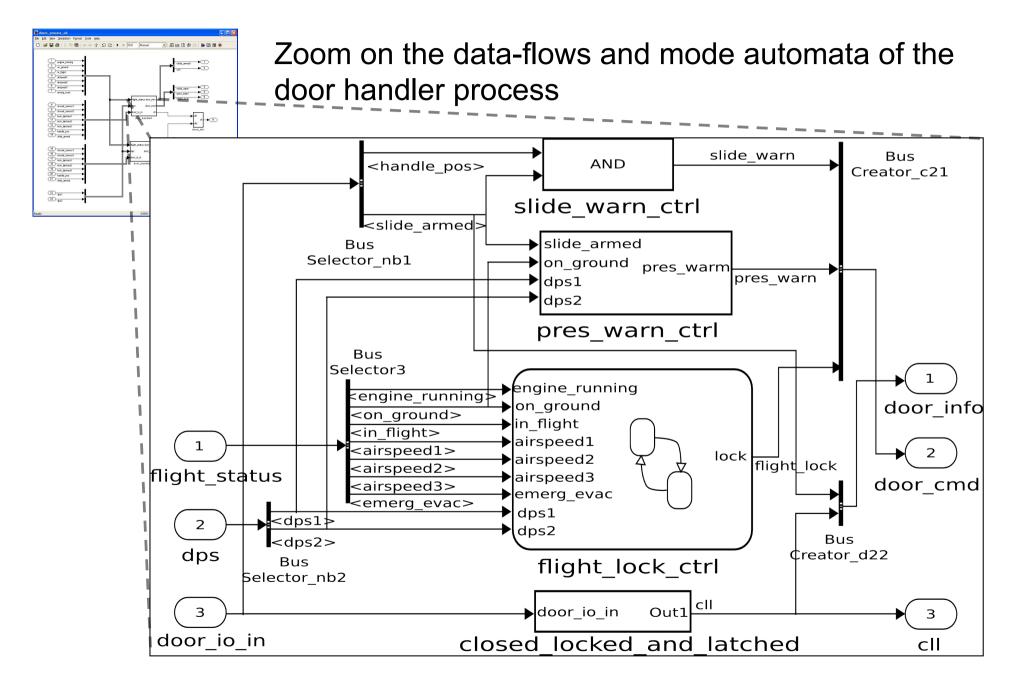
Gene-Auto

A safe subset of Simulink/
Stateflow
Logical time and synchronized
data-flow

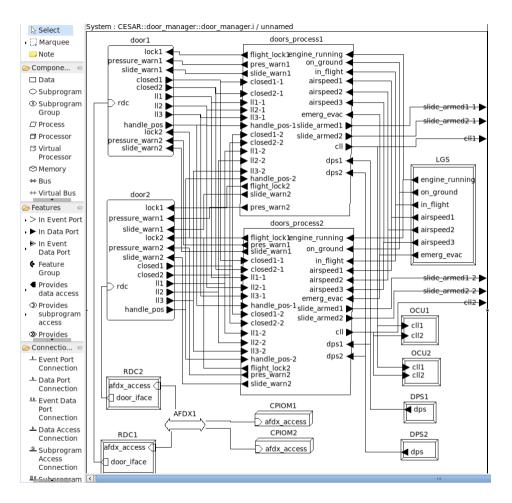
A complete transformation tool-chain with Polychrony



SDSCS functional model (Simulink)



SDSCS architecture model (AADL)



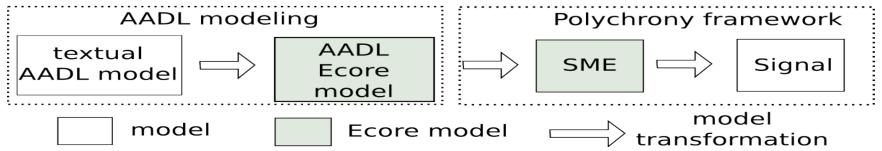
AADL

An SAE standard for high-level, component-based, architecture modeling: application software, execution platform, composites

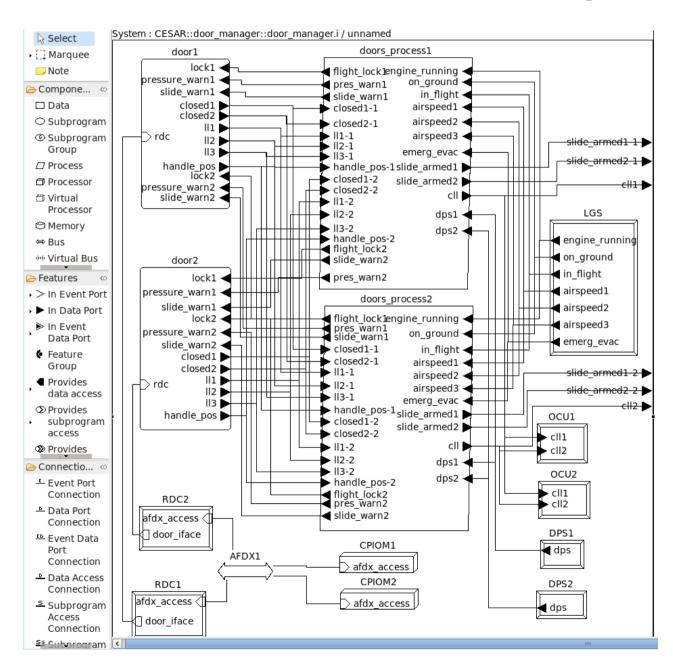
ARINC-653

An API for avionic software supporting the partitioned IMA approach

A complete transformation toolchain with Polychrony



SDSCS architecture model (zoom)



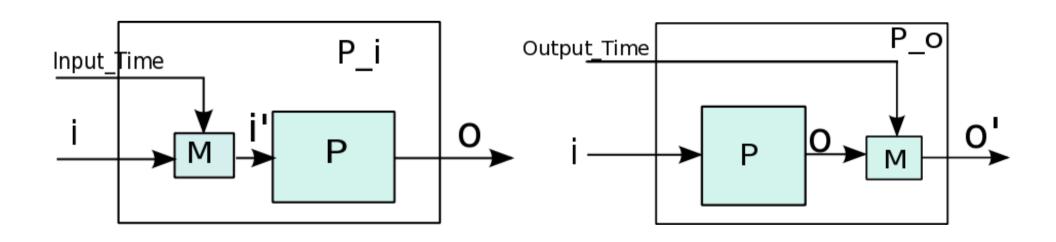
Modeling communication latency

Polychrony

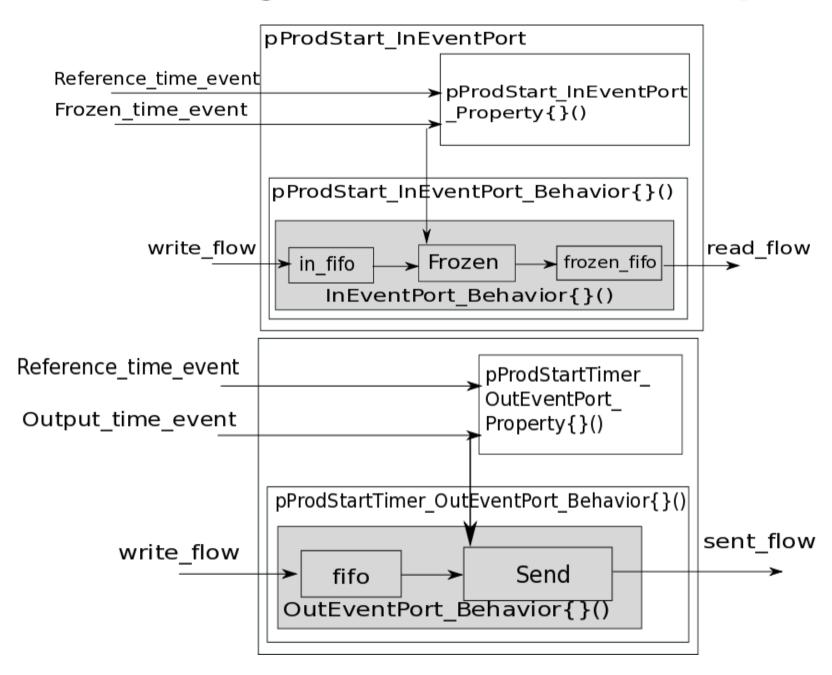
Time is abstracted by Boolean logic Communication is instantaneous

AADL

Thread communicate at specified time intervals A process M models communication delay/timing



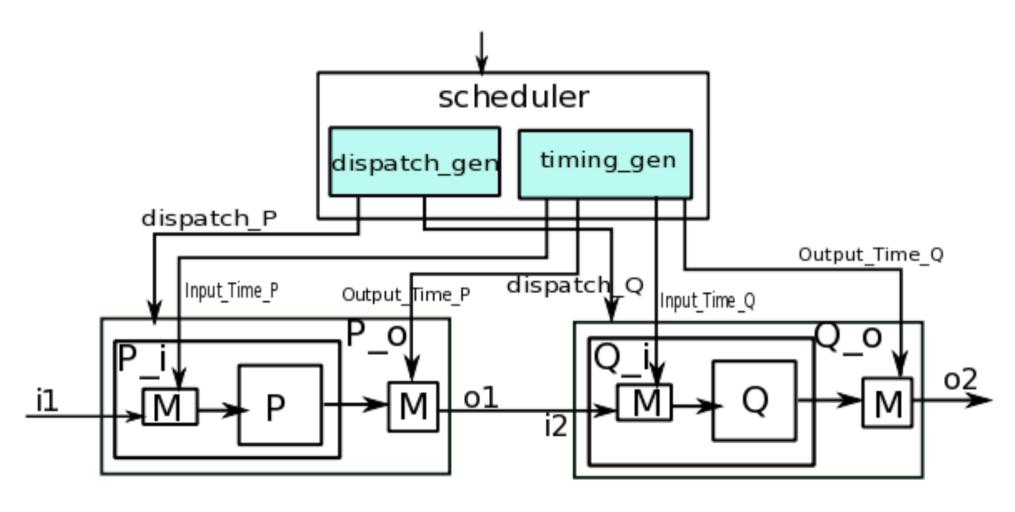
Modeling in/out event/data ports



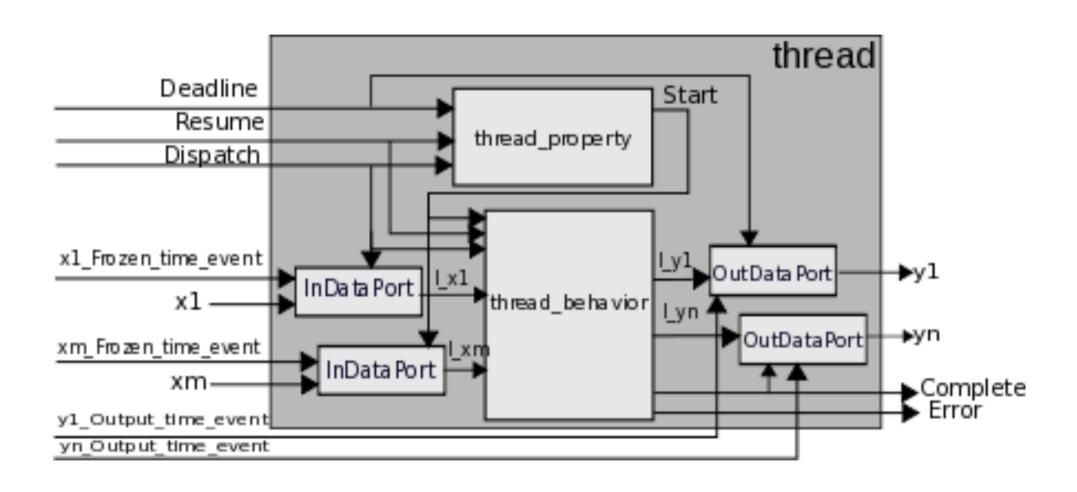
Modeling computation and communication scheduler

Polychrony

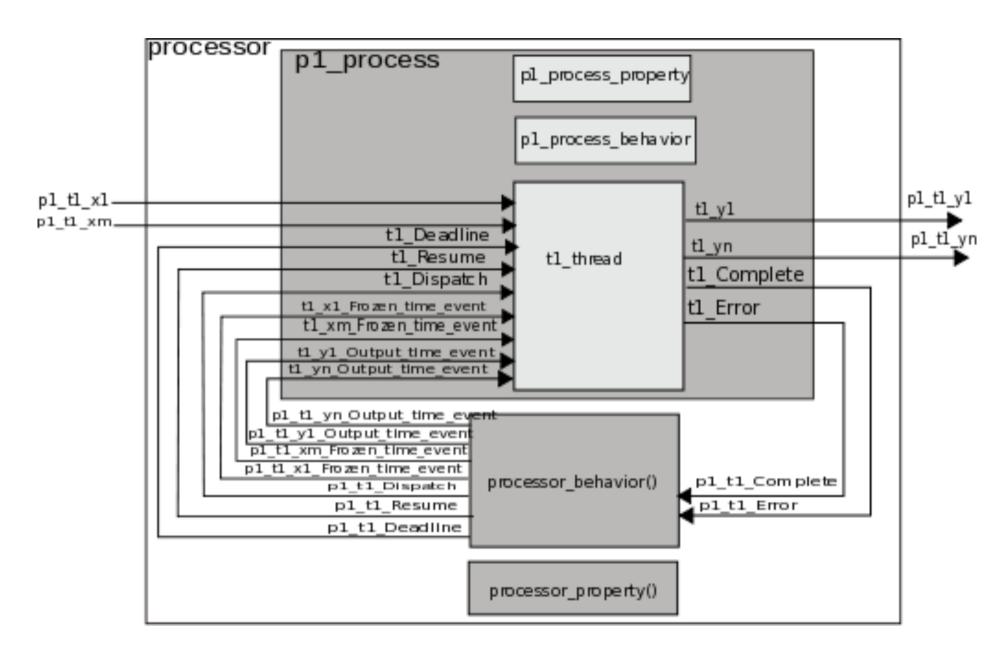
Scheduling of communications can be synthesized



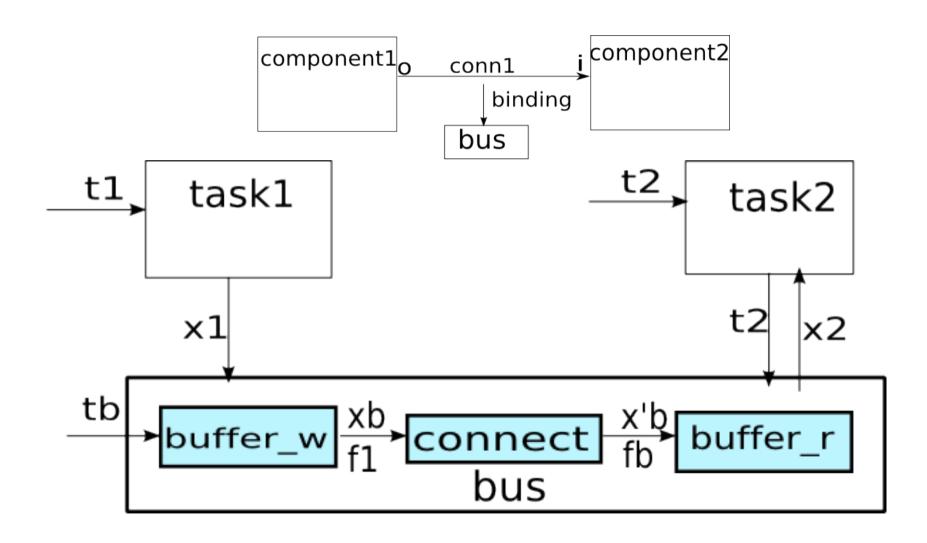
Modeling an AADL thread



Modeling process/processor mapping



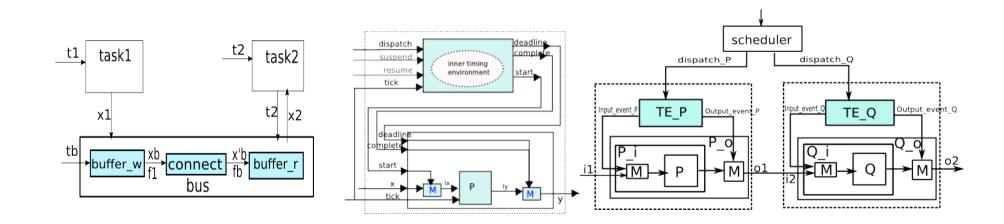
Modeling an AADL bus



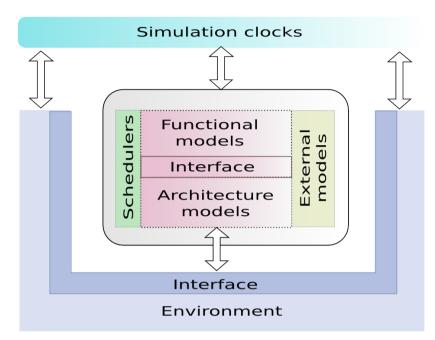
Modeling AADL/RTOS services

Polychrony provides a library of templates to model

- AADL concepts (avionic standard to model architectures)
- ARINC-653 RTOS services (avionic standard to model IMAs)



Simulation model (Polychrony)



Additional models for open system simulation

A simple, non-preemptive, static scheduler

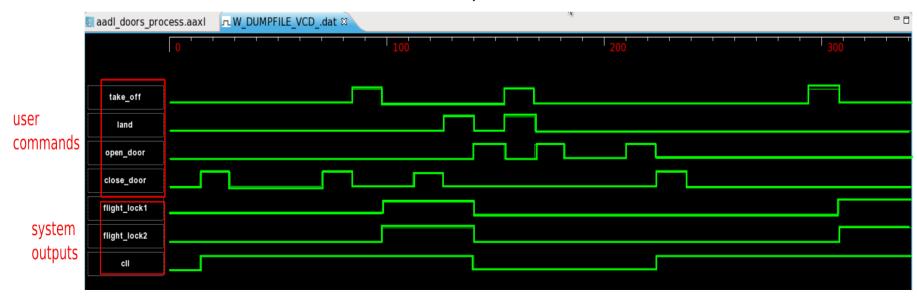
Time intervals are abstracted

Simulation clocks

Reference clocks

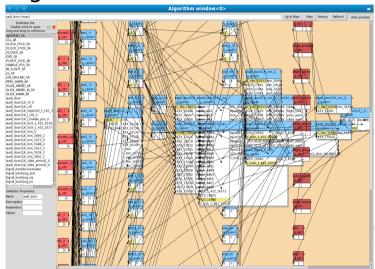
Periodic clocks (threads)

VCD interface - Global simulation clock, interactive and of offline modes

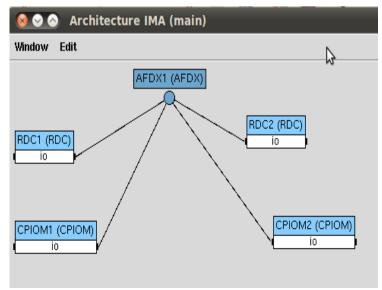


Real-time scheduling (Syndex)

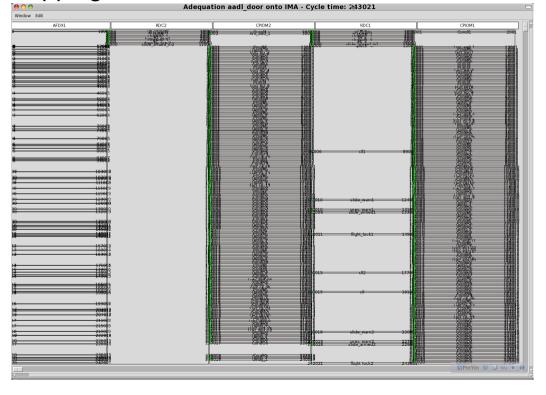
Algorithm



Architecture

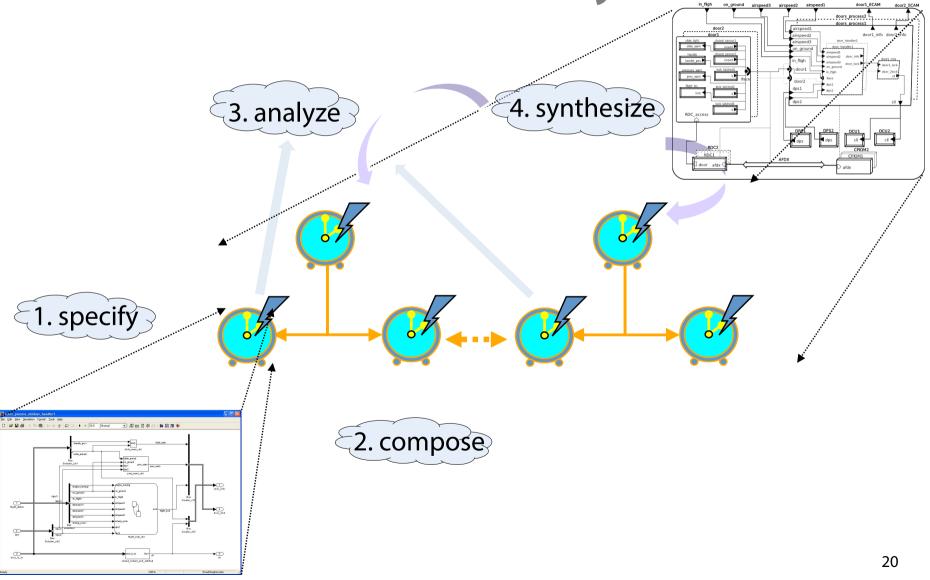


Mapping



Polychrony

A software architecture synthesis tool



POP

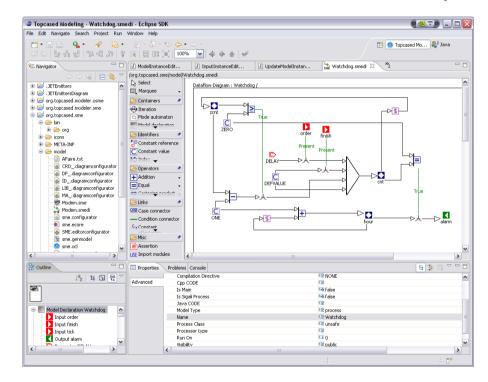
A large toolbox for system architect

A model of computation and communication for software architecture exploration

- Data-flow for computation
- Mode automata for control
- Regular expressions for requirements
- Libraries for services

A toolbox of services

- Code generation
- Model transformation
- Model checking
- Controller synthesis
- Syndex real time scheduling interface

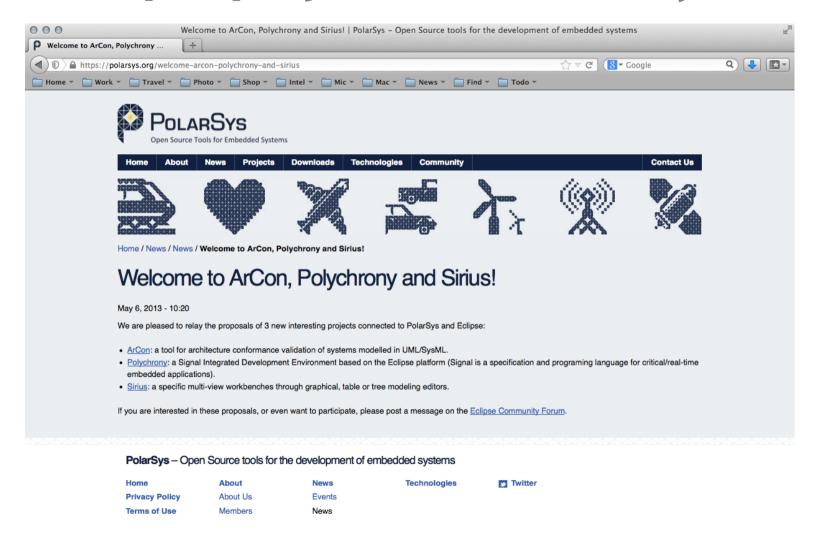


An interactive interface

- Open import functionalities
- Analysis and transformation
- Visualization and traceability

POP

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