

NAME

cheby - chebyshev method with preconditionning

CALLING SEQUENCE

[x,err,iter,flag,res] = cheby(A,b,x0,M,maxi,tol)

PARAMETERS

A	: symmetric positive definite matrix of size n-by-n or function returning A*x
b	: right hand side vector
x0	: initial guess vector (default: zeros(n,1))
M	: preconditioner: matrix or function returning M*x (In the first case, default: eye(n,n))
maxi	: maximum number of iterations (default: n)
tol	: error tolerance (default: 1000*%eps)
x	: solution vector
err	: final residual norm
iter	: number of iterations performed
flag	: 0 = cheby converged to the desired tolerance within maxi iterations 1 = no convergence given maxi res : residual vector

DESCRIPTION

Solves the linear system **Ax=b** using the Chebyshev Method with preconditioning.

The matrix **A** must be a symmetric positive definite matrix.

EXAMPLE

```

A=lehmer(16);
b=rand(16,1);x0=zeros(16,1);
[x,err,iter,flag,res] = cheby(A,b,x0)
M=eye(16,16); max_it=16; tol=1000*%eps;
[x,err,iter,flag,res] = cheby(A,b,x0,M,max_it,tol)

deff("y=precond(x)","y=(M+eye(size(M,1),size(M,2)))*x");
deff("y=matvec(x)","y=(A+eye(size(A,1),size(A,1)))*x";

[x,err,iter,flag,res] = cheby(matvec,b,x0,precond,max_it,tol)

[x,err,iter,flag,res] = cheby(A,b,x0,precond)
[x,err,iter,flag,res] = cheby(matvec,b,x0,M)

```

AUTHOR

Adaptation by Aladin Group of the corresponding code of netlib/mltemplatesdev (Univ. of Tennessee and Oak Ridge National Laboratory) - 20 March 2001.

SEE ALSO

pcg